Use of Network Latency Profiling and Redundancy for Cloud Server Selection

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Abstract—As servers are placed in diverse locations in networked services today, it becomes vital to direct a client’s request to the best server(s) to achieve both high performance and reliability. In this distributed setting, non-negligible latency and server availability become two major concerns, especially for highly-interactive applications. Profiling latencies and sending redundant data have been investigated as solutions to these issues. The notion of a cloudlet in mobile-cloud computing is also relevant in this context, as the cloudlet can supply these solution approaches on behalf of the mobile. In this paper, we investigate the effects of profiling and redundancy on latency when a client has a choice of multiple servers to connect to, using measurements from real experiments and simulations. We devise and test different server selection and data partitioning strategies in terms of profiling and redundancy. Our contribution is to characterize latency behaviors when profiling or redundant data transfer are sent to the servers. Our contribution is to characterize latency behaviors when profiling or redundant data transfer are sent, and create models to estimate latencies for arbitrary data size. Using the estimated latencies at a given data size, we compare the latencies of server selection strategies with and without profiling or redundancy as the number of servers changes and data is partitioned into multiple chunks being sent to the servers. Our contribution is to characterize latency behaviors when profiling or redundant data transfer is adopted for server selection using network measurements. Such characterization helps gain insight in determining the number of servers and which servers should be selected.

Our key findings are summarized as follows. First, if data...
are evenly distributed across servers, latencies decrease initially as more servers take the burden, but eventually increase as more and more servers are involved. Second, if data are distributed greedily—use the server with short response time first (see Section III-A for details)—utilizing the profile of average latencies to servers, latencies decrease and stabilize at the lowest point. Third, when data are evenly distributed to random servers without profiling, latencies do not change much even when more servers participate. Fourth, if data are distributed to random servers, this time redundantly but without profiling, latencies indeed decrease as more servers join, and moreover, latencies further decrease with higher redundancy.

The rest of the paper is organized as follows. Section II discusses our latency measurements. Section III discusses server selection and data partitioning algorithms using our measured latencies and their analysis. We summarize related work in Section IV and conclude in Section V.

II. MEASUREMENT OF LATENCIES

We discuss our approach for obtaining latency measurements and latency estimation, and then present the results.

A. Configurations and Metrics

We conduct experiments on PlanetLab in which 1,168 computers (or nodes) are available at 550 sites around the world [11]. Also, the geographically diverse nodes in PlanetLab allow us to test different parts of the network with more comprehensive observations. We record our measurement data in February 2013. Five nodes operate as clients, and a total of 150 nodes are randomly selected as servers: 36 in North America, 6 in South America, 27 in Asia, 58 in Europe, and 3 in Oceania. Each client sends data to 30 servers (again randomly selected) over TCP, and we are able to obtain valid measurement data from 130 nodes out of the 150 servers. A client sends five different data sizes, namely 8 KB, 64 KB, 256 KB, 512 KB and 1 MB, giving 400 measurements for each data size totally, with 200 over the weekends and the other 200 on weekdays. This provides us with 2,000 measurements per server and totally 300,000 measurements.

We use latency as the primary performance metric. We measure round-trip time as latency, which is defined as the elapsed time between sending the first packet by the client and receiving an acknowledgment message for the last packet (at the application layer) from the destination server via the same connection. Due to clock drifts (clocks at the sender and the receiver are not synchronized), it is nearly impossible to measure one-way latency from the sender to the receiver. We analyze the latency distributions and basic statistics like average and standard deviation when various file sizes are transferred to see their characteristics. Throughput can also be estimated indirectly using the inverse of our latency measurements as needed.

B. Results

Figure 1 depicts the latencies measured at three servers (Argentina, Germany, and the West Coast of the United States) as an example out of the 130 servers. The dots denote the average latencies measured when the five different sizes of data are sent. The error bars show the standard deviation of the measured latencies. Both of the latencies and standard deviations increase as data size increases for all of the servers. The latency increase fits well a linear model, and thus we estimate latencies for other data sizes using linear regression. The resulting estimated latencies are represented as a line in the figure, and the values for $a$ and $b$ in the linear model, $y = ax + b$, are shown in Table I where $x$ is data size and $y$ is latency.

<table>
<thead>
<tr>
<th>Server</th>
<th>$a$</th>
<th>$b$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Buenos Aires</td>
<td>23.535531</td>
<td>13.3258792</td>
</tr>
<tr>
<td>Berlin</td>
<td>22.162589</td>
<td>40.1769235</td>
</tr>
<tr>
<td>Oregon</td>
<td>10.825825</td>
<td>25.1895639</td>
</tr>
</tbody>
</table>

The measured latencies will be used to estimate and profile latency to a target server for an arbitrary data size.
when original data can be split into multiple chunks and be sent to multiple servers. For example, if 1 MB data are evenly distributed and sent to two servers, the linear model for the first server is used to estimate the latency for the first chunk of 512 KB and the linear model for the second server is used to compute the latency for the other half chunk. More details are discussed in the following section.

III. USE OF ESTIMATED LATENCIES

Using the estimated latencies, we compare different server selection strategies in detail in this section. Our results provide insight and tradeoffs to be considered when profiling latencies for server selection. We consider data redundancy as well in this comparison.

A. Server Selection Algorithms

Latencies to servers vary widely depending on the locations of the servers and on the network conditions, as shown in the previous section. In some instances, a client has the option to divide data into smaller chunks and send these data chunks to a set of servers (possibly a different number). An interesting question is whether the latency linear model computed for each server can be utilized for the client to select server(s) to minimize the latency of its data transfer. Motivated by this question, we devise three data partitioning and server selection algorithms, namely random, fixed, and greedy, and conduct simulations, based on the estimated latencies as well as real experiments. Note that these algorithms allow requests to be sent to multiple servers concurrently and be processed in parallel.

In the random algorithm, a client sends $m$ bytes data to $n$ randomly selected servers located in different places for $n \geq 1$. The data are evenly divided among servers, i.e., $\frac{m}{n}$ bytes to each server. Moreover, the client may send copies of data chunks to more servers redundantly. In this case, it is possible for the client to receive multiple responses for a data chunk due to this redundancy. Latency in this case is defined as the elapsed time from when the client starts sending the first data chunk until when the first responses for all of the data chunks are received. The redundant data transfer thus exploits more servers and networks, and hence reduces latency by increasing the probability that a response returns earlier.

The fixed algorithm is the same as the random algorithm except 1) there is no redundancy, and 2) there is server selection. In this algorithm, the servers are sorted in non-decreasing order in terms of the average estimated latencies, and then the first $n$ servers from the lowest latency upward are selected when sending the data to $n$ servers. Latency is the time that it takes for the last response to be returned (note that there is no redundant response).

In the greedy algorithm, we first order the servers by their latencies like the fixed algorithm, and give the first chunk to the server that can respond in the minimum amount of time. The size of the first chunk is the smallest possible that the data can be divided into. We then give the second chunk to the server that can complete in the minimum amount of time. Note that this may be the same server as given the first data chunk if the time for the first server to complete both of the first and second data chunks is less than the time for the second server to complete just data chunk two. We continue in this way, greedily selecting the server for each chunk in turn. This latency is indeed the lower bound of latency. Since finding a set of such data chunks is inherently a complex optimization problem, we use the approximation algorithm described in Algorithm 1 for our simulations and experiments. The main idea is to move a portion of data $(a(i)u$ in line 8) from server($i$) when $i = 1, \ldots, k-1$ to a newly added server($k$), and iterate the process until finding the minimum latency.

Algorithm 1 Approximated Greedy Algorithm

\begin{verbatim}
1: for $k = 2 \rightarrow n$ do
2: flag $\leftarrow$ true
3: while flag do
4: for all server($i$) as $i = 1 \rightarrow k - 1$ do
5: temp($i$) $\leftarrow$ data($i$)
6: data($i$) $\leftarrow$ data($i$) $-$ a($i$)u
7: end for
8: data($k$) = totalData - $\sum_{i=1}^{k-1}$ data($i$)
9: curLat $\leftarrow$ $\infty$
10: if max(lat(0), lat(1), \ldots, lat($k$)) $<$ curLat then
11: flag $\leftarrow$ true
12: curLat $\leftarrow$ max(lat(0), lat(1), \ldots, lat($k$))
13: else
14: flag $\leftarrow$ false
15: for all server($i$) as $i = 1 \rightarrow k - 1$ do
16: data($i$) $\leftarrow$ temp($i$)
17: end for
18: end if
19: end while
20: end for
\end{verbatim}

B. Results

We compare latencies estimated for the three algorithms using Monte-Carlo simulations and real experiments. For the simulations, we randomly generate latency $L_i$ following a distribution with average latency $E_i$ and standard deviation $\sigma_i$ for a given data chunk size. We find that the latencies of the linear models (Figure 1) approximate a Gaussian distribution well with different mean and standard deviation values, and $E_i$ and $\sigma_i$ are estimated based on that. We use Gaussian distributions with interpolated mean and standard deviation values for the points for which measurement data are not available (e.g., when data size is 400 KB in Figure 1). We then run the random, fixed, and greedy algorithms, and
compute the total latency, which is $\max(L_1, L_2, \ldots, L_n)$ for $n$ participating servers, if there is no redundancy. This process repeats a sufficiently large number of times. Note that in the figures, R1 represents the random algorithm with the client sending only a single copy of data (no redundancy), R3 is the random algorithm with the client sending three copies of the data (redundancy), R5 sends five copies, and R10 sends ten copies.

In Figure 2(a), we show the latencies estimated from the simulations when data are partitioned and sent using the random algorithm. Each random algorithm sends a different number of duplicate copies as defined above. The number of servers changes from 1 to 55 and 1 MB data are sent. For each algorithm, we run 100 simulations with different random number generator seeds for selecting servers and average the results. No server is selected for more than one copy of data chunk, i.e., each copy is sent to a different server. This algorithm increases reliability in case of server or network failures–responses return with higher probability with redundancy. The algorithm, however, reduces the total number of servers that a client can reach when copies of data chunks are sent as discussed. For example, the client in R3 can use only one third of the available servers since three copies of a data chunk are issued.

In addition, we run real experiments over the wide-area network to validate our simulation results. For the experiments, we are able to collect valid data from 41 servers out of 55 randomly chosen PlanetLab nodes (refer to Section II for details) providing 400 measurements for latency during weekdays as a node at Yale University sends 1 MB data to the chosen servers. Again, we repeat the experiments 100 times. As Figure 2(b) shows, the latencies from the real experiments behave similar to those from the simulations for all R1, R3, R5, and R10. In comparison to the simulation results (Figure 2(a)), the latencies are in general higher (20–30%) because the latencies from the experiments are measured during weekday daytime while the simulation latencies are profiled based on the latencies measured at different days and times including weekdays, weekends, daytime and night.

The estimated latencies for the fixed and greedy algorithms are shown in Figure 3. The latencies from both the simulation and the real experiments are presented and compared. The experimental setup is the same as that of the random algorithm as discussed above. As shown in the figure, the number of servers in the experiments are no more than ten due to the limited number of concurrent TCP sessions at the sender. The latencies from the experiments behave nearly identical to the latencies from the simulations for the fixed algorithm; the trends of the latencies from the experiments and simulations are similar for the greedy algorithm. Due to the same reason as discussed above for the random algorithm (Figure 2(b)), the latencies from the experiments are higher than those from the simulations.

Figure 4 shows the latencies of all the three algorithms together computed from the simulations for comparison.

From these results, we observe several interesting phenomena. First, the latencies obtained from the random algorithm without redundancy (R1) do not change significantly as the number of servers changes except an extremely few servers (1–2), and are approximately five times higher than those of the greedy algorithm. The server that responds last determines the latency since the latency is $\max(L_1, L_2, \ldots, L_n)$, and that server is selected at random regardless of the number of servers. Second, the latencies with redundancy (R3, R5, and R10) decrease as more servers are selected, and drop more sharply with higher redundancy (more copies), e.g., R10 drops faster than R3 and the latency of R10 is 2.5 times lower than the latency of R3 when the number of servers is 5. As more servers are involved for more copies of data chunks, the probability that a response for a data chunk returns earlier increases. The decrease of latencies, however, does not continue beyond a certain number of servers (e.g., seven for R3 in Figure 2) because there are not enough redundant copies to explore the increasingly diverse servers.

Third, the latencies in the fixed algorithm decrease and then increase beyond a certain number of servers–around five to six in Figure 3(a). Latency initially decreases as more servers take the burden of data, while latency increases later as the long latencies of servers that join later overshadow the benefits of burden sharing. Fourth, the latencies in the greedy algorithm decrease to the lowest point and stabilize similar to the random algorithm with high redundancy. The greedy algorithm seeks optimal server selection in order to minimize latency. The latencies do not continue to decrease since the data transfer requires fundamental overheads like propagation delay.
C. Profiling versus Redundancy

In a distributed computing setting like cloud computing, a client often relies on profiling based on network measurements to select the optimum group of servers and the way data are partitioned in order to meet its performance goals, e.g., minimal latency. A profiler probes the network, gathers measurements from the probe, analyzes the measurements, and creates the profiles of the measurements as functions of different parameters like days (e.g., weekdays or weekends), time (e.g., morning or night), and geographical locations. Of course, this probe and analysis needs to repeat periodically. Using the profiles, the user can run an intelligent algorithm to compute the best group of servers without much computational overhead. The results and analysis in the previous section re-iterate the importance of this intelligent algorithm in profiling. For example, the profiler can find out which six servers would provide the minimal latency when data size is 1 MB using the results in Figure 3.

Our results also imply that redundancy can contribute considerably to reducing latency in a reasonably simple way. As illustrated in Figure 4, a large amount of redundancy (R10) can reduce the latency compared with a random algorithm with no redundancy (R1) by 50%, approaching the latency achieved by the fixed and greedy algorithms. While redundancy injects many more packets into the network, it does not require the profiling overhead for network probes and estimation.

Additionally, these properties open the potential of hybrid dynamic profiling in which both sophisticated profiling and relatively simplistic redundancy are used together to select target servers. For frequent and long-lived network flows, profiling with periodic network probes helps, while short-lived flows can take advantage of redundancy without much overhead for network measurement and computing. It is also feasible that the latencies measured from on-going flows with redundancy are fed to the profiler and used as network measurements.
IV. RELATED WORK

There have been attempts to measure latency accurately in the literature. IDMaps [12] deploys end hosts at strategic locations, gathers latencies, and then synthesizes them to estimate the latency between end hosts. GNP [13] estimates latency based on coordinates that are computed using landmark hosts. King [14] is a tool that estimates the latency between arbitrary end hosts by using recursive DNS queries without requiring extra infrastructure. Vivaldi [15] helps an end host compute its Internet coordinate for localization using only a few latency measurements in a fully distributed way. Madhyastha et al. [16] predict latency based on measurements of the Internet routing topology, connectivity, and policy. Netvigator [17] is a network proximity and latency estimation tool using landmark hosts and intermediate routers. Zhang et al. analyze and characterize Internet delays using these tools [18].

The measured latencies are used for server selection in routing, content distribution networks, and cloud computing. DONAR [3] is a distributed system that determines the best replica server considering both client and server loads, cost, and locations. Related to DONAR, several studies were conducted for content retrieval and server selection with the cloud. Khosla et al. investigate the performance degradation problem in cloud-based DNS [19]. Xu and Li propose a practical framework for cloud datacenter selection with special attention to fairness [20], and study the problem of joint request mapping and response routing [21]. CloudGPS [22] presents a server selection algorithm in the cloud that enables ISPs to configure a global performance function for low latency or cost in a scalable and ISP-friendly way. Given the high variability in performance of cloud services, Dealer [23] seeks to minimize response time for geo-distributed, interactive and multi-tier applications.

Recent advances in mobile, cloud and networking technologies enable mobile devices to offload heavy computation seamlessly, transparently, and cost-effectively to the cloud, in which rich resources are available [4], [6], [5], [24]. These mobile-cloud computing architectures have a profiler that provides estimated duration times of input executables based on measurements for devices, programs, or networks. Our results suggest that cloudlets can be used to support mobile-cloud computing by enabling network latency profiling in conjunction with intelligent server selection algorithms to connect to the best-performing server(s) in the cloud. Alternatively, the mobile, which cannot easily profile the network latencies, can achieve good latency performance through the use of redundancy as discussed in [25].

V. CONCLUSIONS AND FUTURE WORK

We have studied latency profiling for server selection using network measurements in distributed and cloud computing. The objective of this study is to understand the behaviors of latencies as a client has options to choose among different groups of servers, and to design efficient and practical algorithms that select servers with minimal latency. Using models based on measured latencies to servers, we have tested the random, fixed and greedy data partitioning and server selection algorithms. Our results indicate that latencies can be reduced using the fixed algorithm compared to the random strategy, and can be nearly optimized as data are partitioned and sent to servers greedily. Moreover, the random algorithm can reduce latency significantly if data are sent redundantly. This implies the potential of dynamic profiling in which the greedy strategy is used for long-lived regular traffic while the random strategy with redundancy is used for short-lived traffic.

We have developed a mobile-cloud architecture that provides a face recognition platform on a mobile device. We will extend this architecture to incorporate our dynamic profiling and redundancy ideas and results. Highly interactive applications including face recognition in the distributed setting would benefit significantly from such profiling and redundancy. We are also considering an intermediate device called a cloudlet for accelerating the execution of the face recognition application. The computation for profiling and redundancy can be performed at the cloudlet for faster processing.

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REFERENCES


