

Computing and Counting the Longest Paths on Circular-Arc Graphs in Polynomial Time

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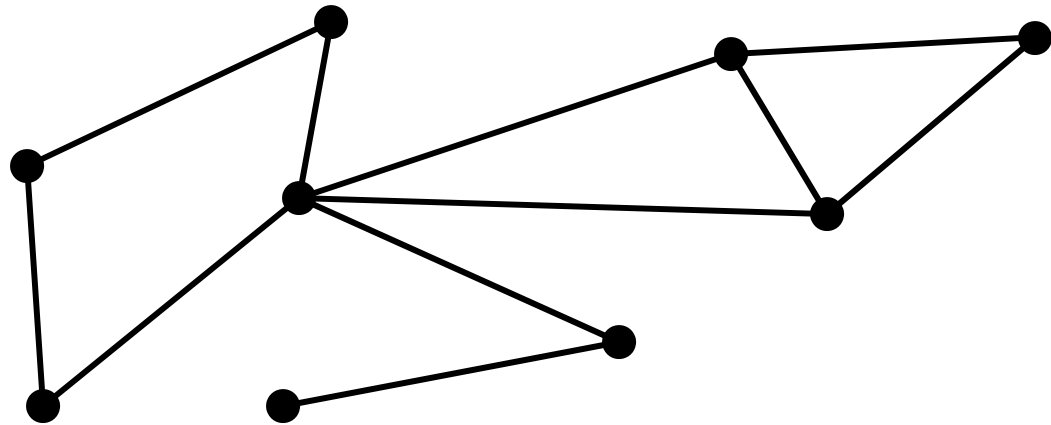
LAGOS 2011, March 29, 2011

The Longest Path Problem

Input: an undirected graph G

Output: a path with the largest possible length

Example:

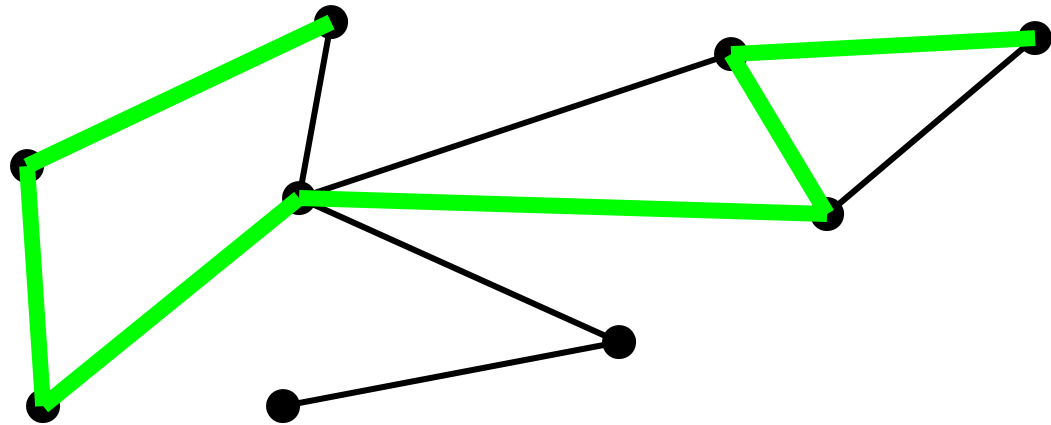


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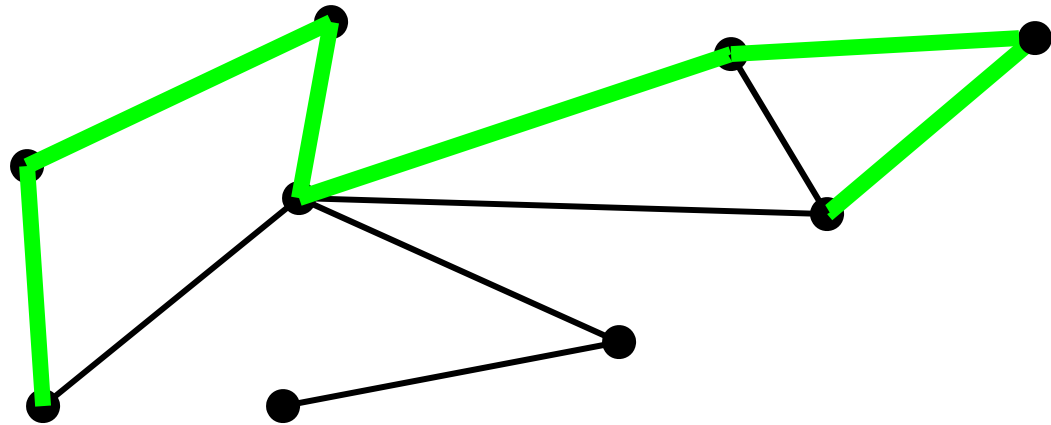


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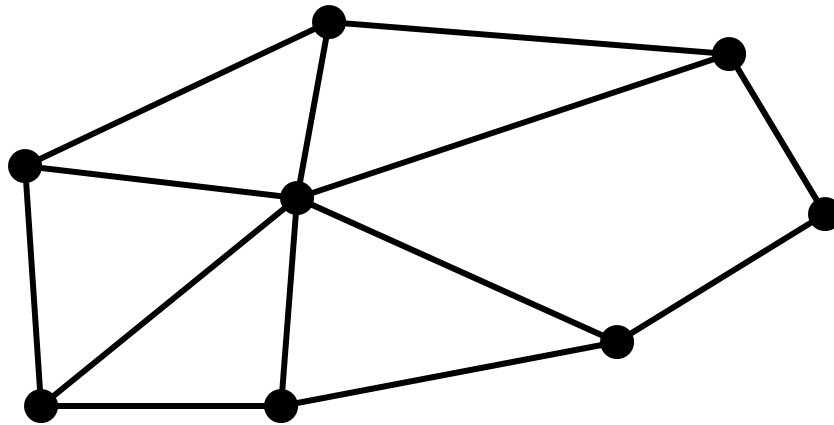


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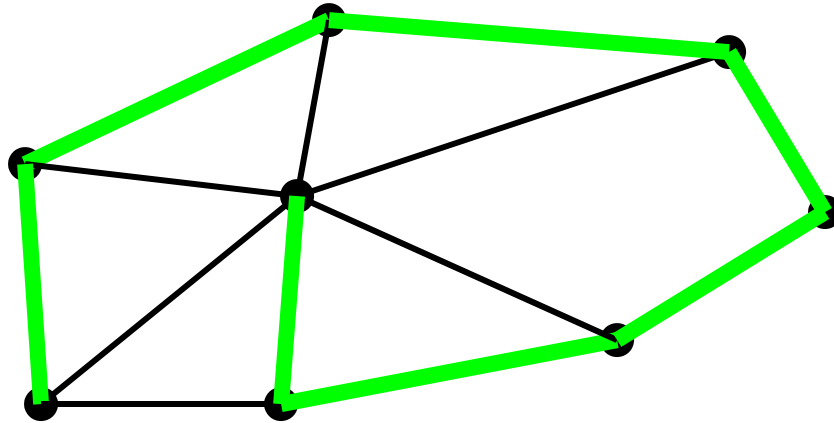


The Longest Path Problem

Input: an undirected graph G

Output: a path with the largest possible length

Example:



Hamiltonian path: a path going through all vertices

Note: Longest Path generalizes the Hamiltonian path problem, hence Longest Path is NP-hard

The Longest Path Problem

Hamiltonian and Longest Path are NP-hard on:

- general graphs
- planar graphs
- bipartite graphs
- split graphs
- ... [see, e.g., Mertzios PhD Thesis '09 for the references]

Inapproximability results [Karger-Motwani-Ramkumar '97]:

- For any $\epsilon \in (0,1)$, finding a path of length $n - n^\epsilon$ in a graph with a Hamiltonian path is NP-hard
- If $P \neq NP$, no constant-factor approx. for Longest Path

The Longest Path Problem - Related Works

Path problems in polynomial time:

- Ham. Path on
 - proper interval graphs [Bertossi '83]
 - interval graphs [Arikati-Rangan '90, Keil '85]
 - circular-arc graphs [Damaschke '93, Hung-Chang-Lai '09, Shih-Chern-Hsu '92]
 - cocomparability graphs [Hung-Chang '06, Hung-Chang-Lai '09]

The Longest Path Problem - Related Works

Path problems in polynomial time:

- Longest path - very recent:
 - trees [Bulterman-van der Sommen-Zwaan-Verhoeff-van Gasteren-Feijen '02]
 - weighted trees and block graphs [Uehara-Uno '04]
 - bipartite permutation graphs [Uehara-Valiente '07]
 - ptolemaic graphs [Takahara-Teramoto-Uehara '08]
- interval graphs [Ioannidou-Mertzios-Nikolopoulos '09]
- cocomparability graphs [Ioannidou-Nikolopoulos '10 - $O(n^8)$, Mertzios-Corneil '10 - $O(n^4)$]

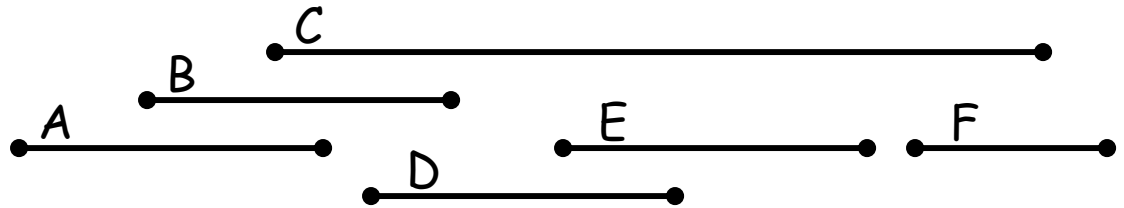
Examples of applications of Longest Path:

e.g., computational biology [Colinge-Bennett '07, Cuntz-Borst '07]

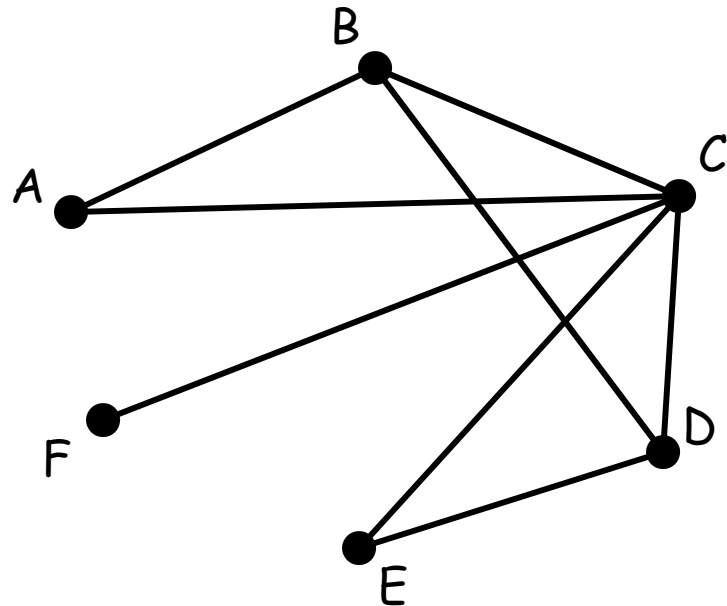
Interval vs. Circular-Arc Graphs

Interval graphs: intersection graphs of intervals

An interval graph representation:



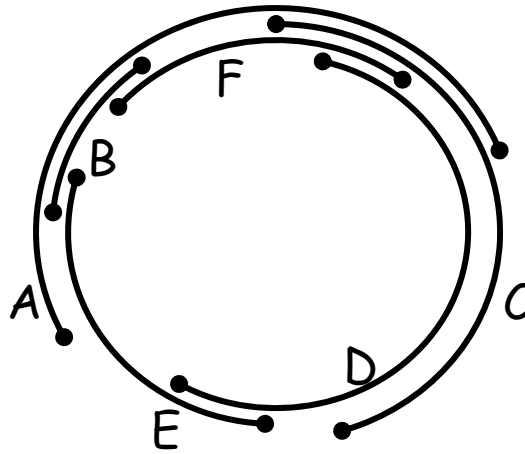
The corresponding graph:



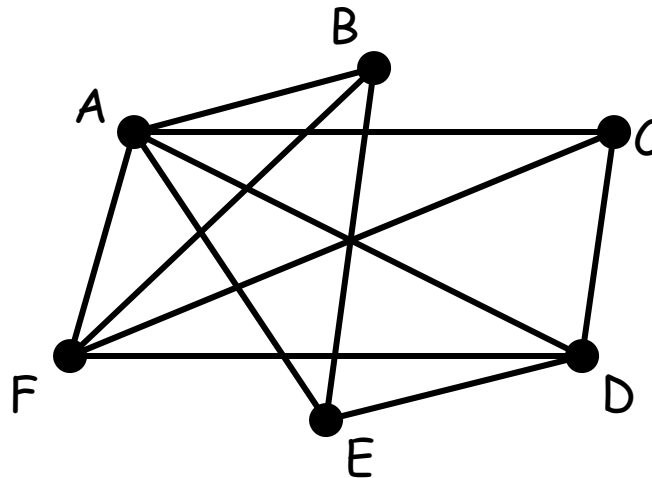
Interval vs. Circular-Arc Graphs

Circular-arc graphs: intersection graphs of arcs on a circle

A circular-arc graph representation:



The corresponding graph:



Interval vs. Circular-Arc Graphs

For some problems, interval graphs are very different from circular-arc graphs, e.g.:

Minimum chromatic number (coloring):

- polynomial-time for interval graphs [Garey-Johnson-Miller-Papadimitriou '80]
- NP-complete for circular-arc graphs [e.g., Golumbic '04]

Motivation for circular-arc graphs:

- scheduling periodic tasks

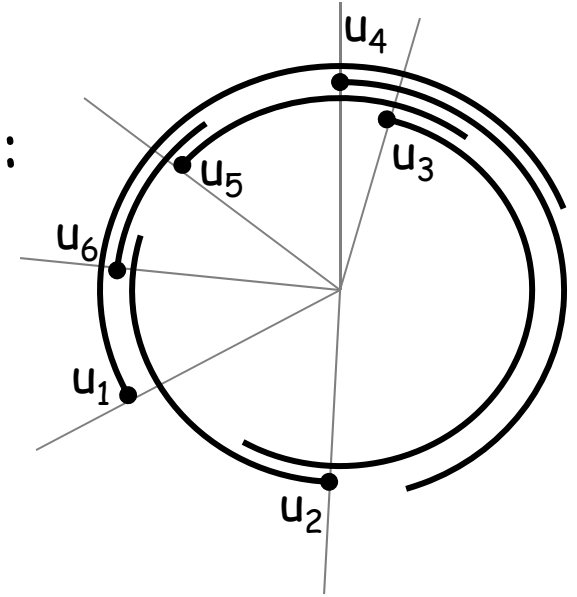
Our contributions

- Reduction from circular-arc graphs to interval graphs
- Simplification of the algorithm for interval graphs by Ioannidou, Mertzios, and Nikolopoulos '09
- Counting and sampling of ("normal") longest paths

Reduction: circular-arc \rightarrow interval graphs

Some terminology:

- denoting arcs by their right end-points:
- right-end ordering of arcs:



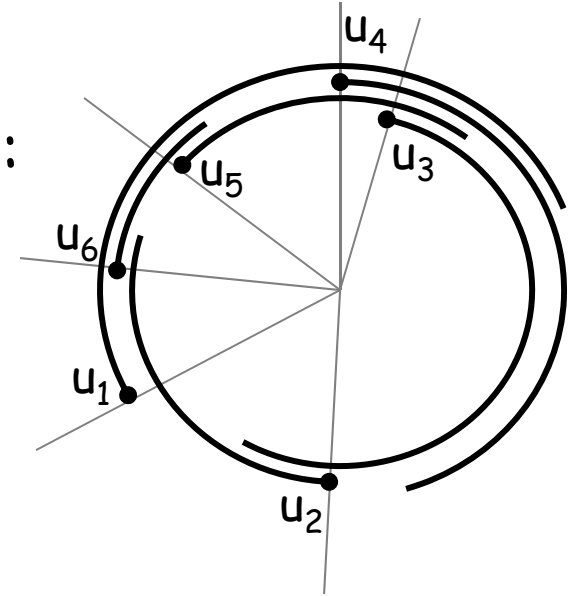
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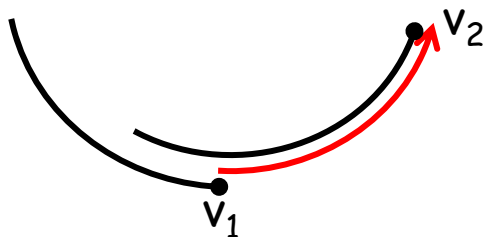
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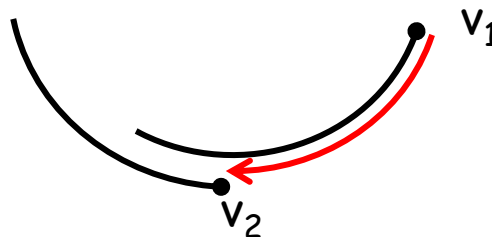
- edge v_1v_2 is:



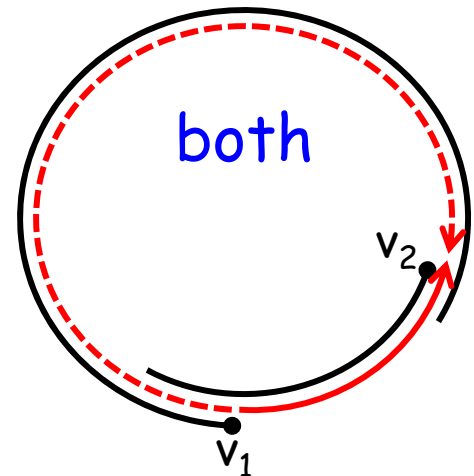
right-going



left-going



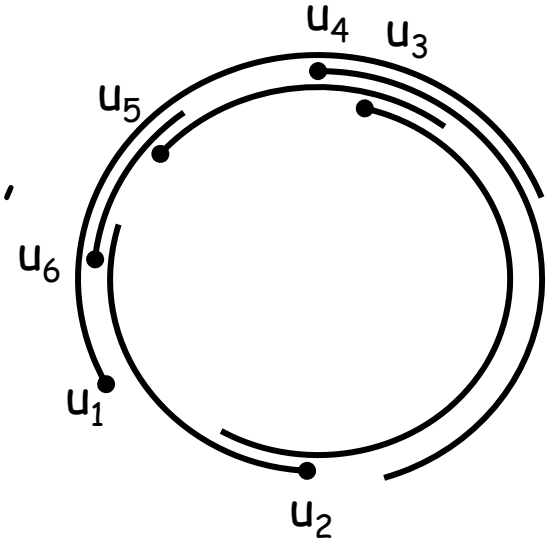
both



Reduction: circular-arc \rightarrow interval graphs

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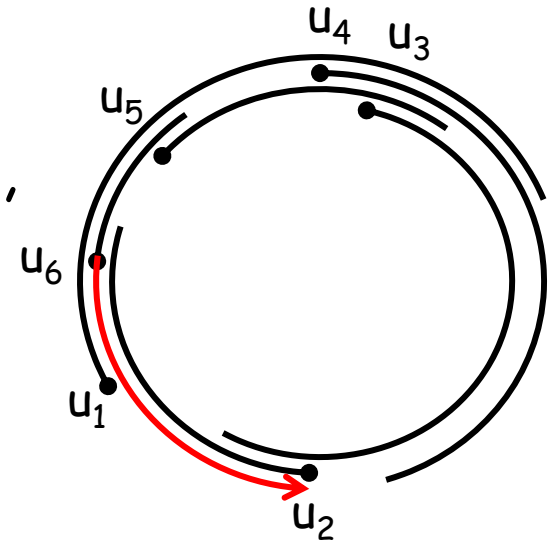
- **path-arc representation:**
representing edges by the red arcs,
e.g. path $u_6 u_2 u_3 u_1 u_4 u_5$:



Reduction: circular-arc \rightarrow interval graphs

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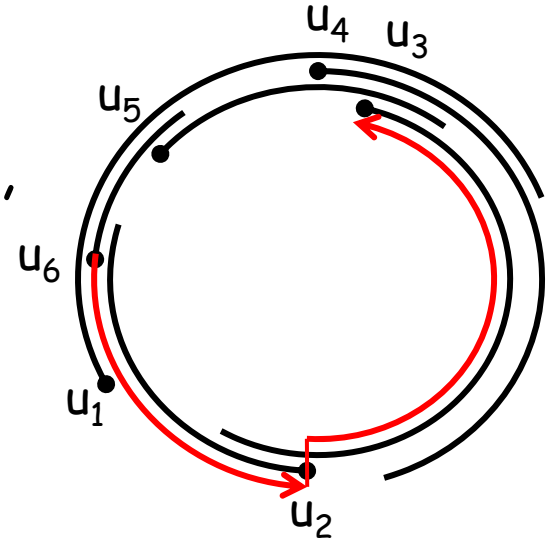
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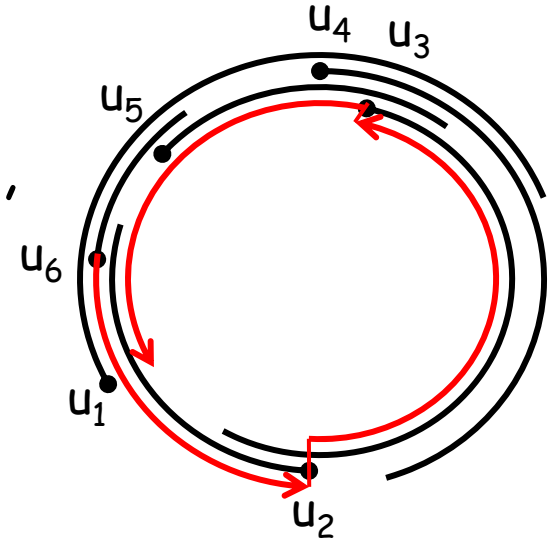
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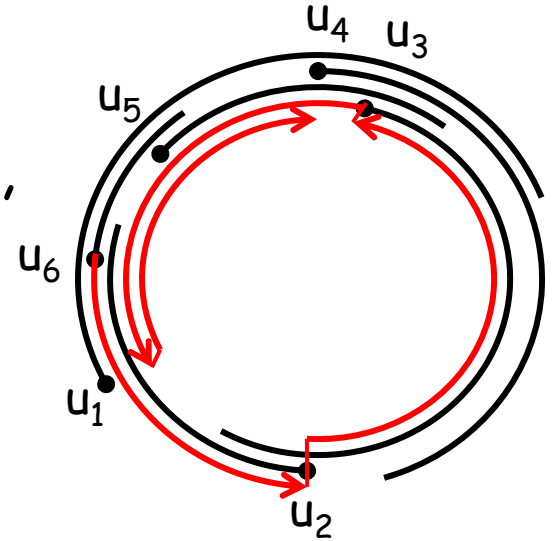
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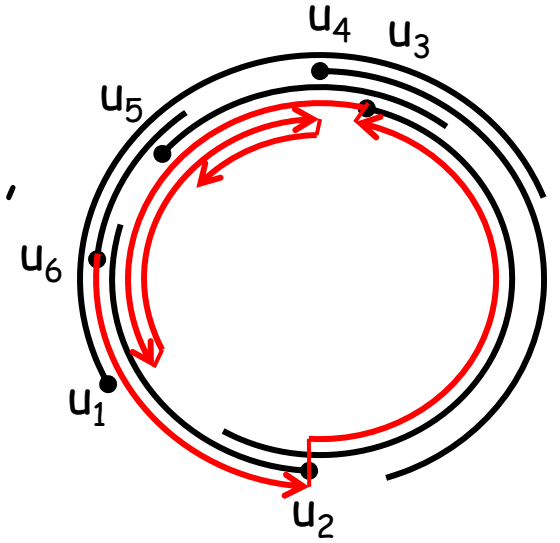
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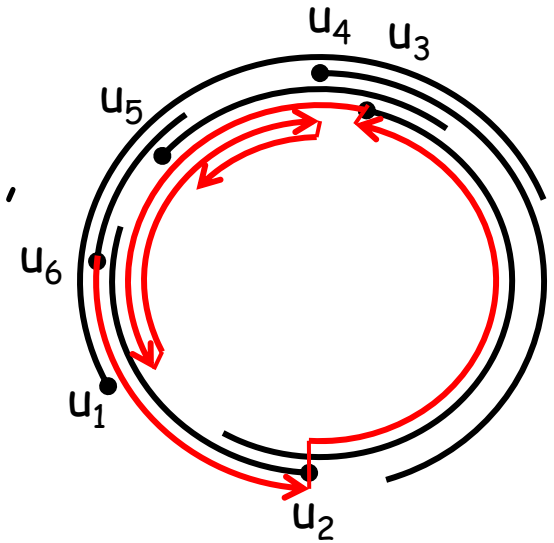
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- **path-arc representation:**
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Idea: for **every** path P , there exists a path P' on the same set of vertices with path-arc representation that does not cover the entire circle

Reduction: circular-arc \rightarrow interval graphs

Some terminology:

- **path-arc representation:**

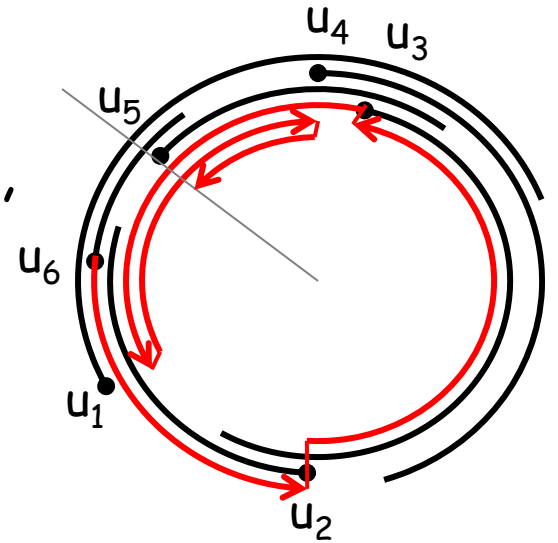
representing edges by the red arcs,
e.g. path $u_6 u_2 u_3 u_1 u_4 u_5$:

- given a path-arc representation:

- **right-cut** and **left-cut** at a vertex u :

number of right- and left-going red arcs containing u ,
e.g. for u_5 : right-cut = left-cut = 1

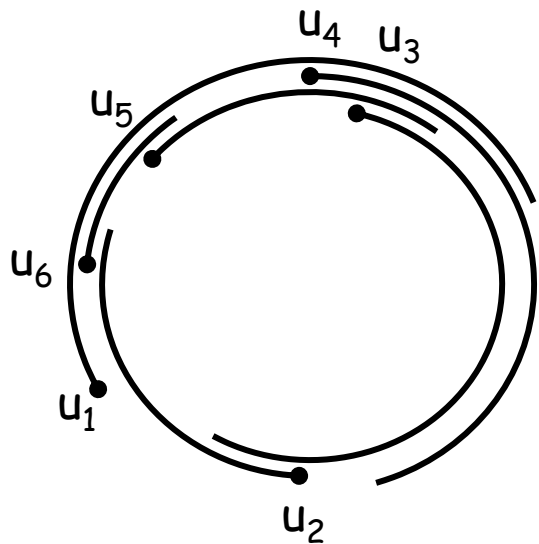
- **cut** at a vertex u = right-cut + left-cut



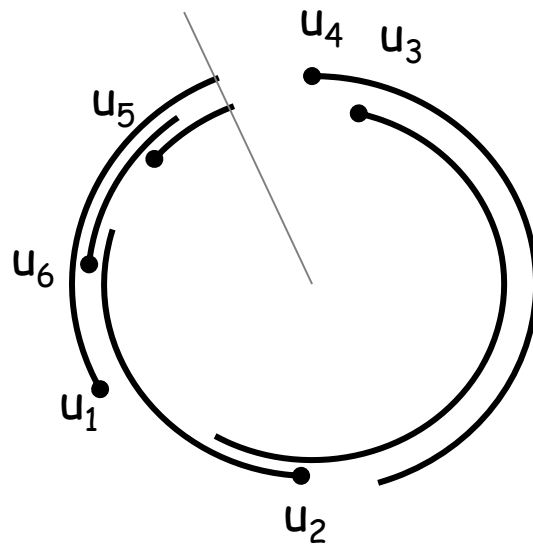
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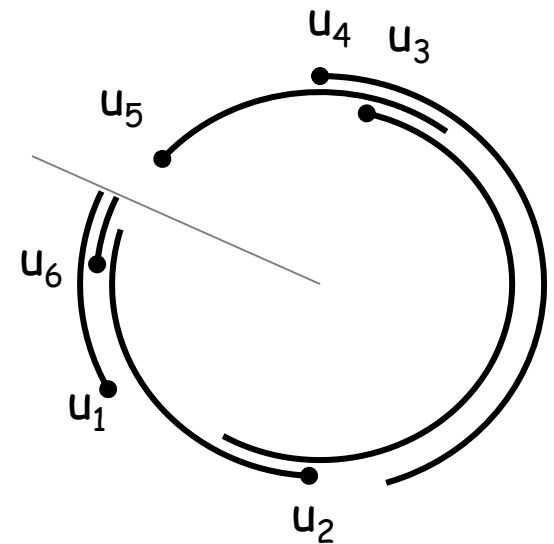
- cutting the circle before/after a vertex, e.g. for u_5 :



original
representation



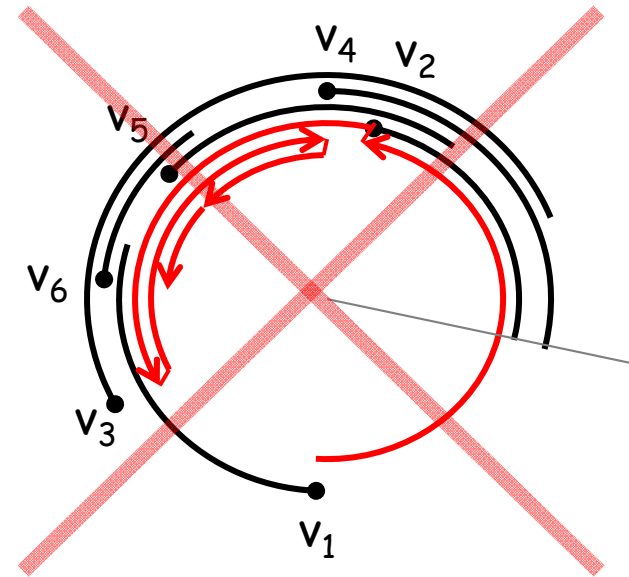
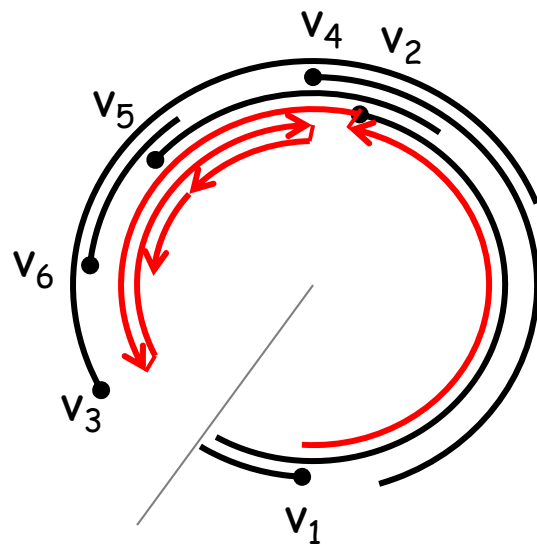
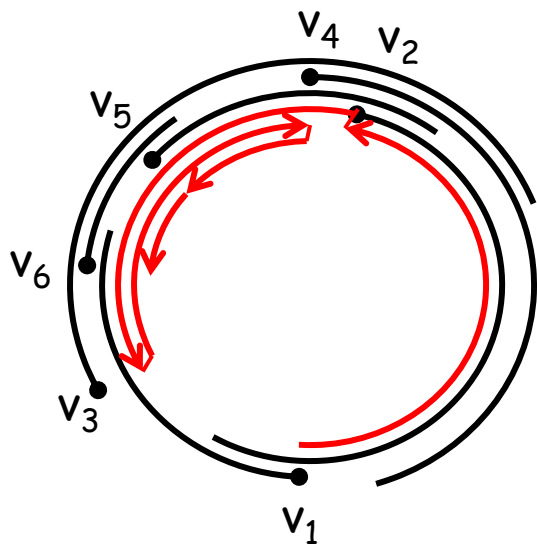
representation
for cut before u_5
 \rightarrow get graph G_{u_5}



representation
for cut after u_5

Reduction: circular-arc \rightarrow interval graphs

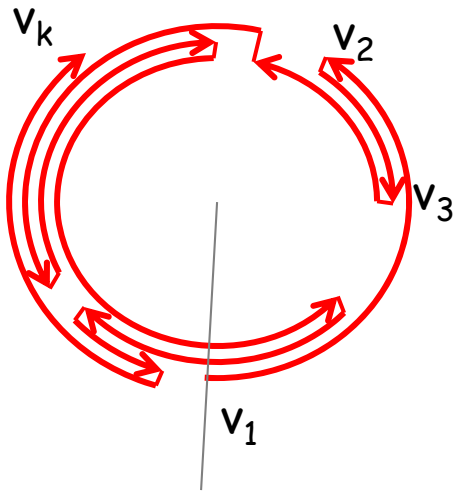
Lemma 1: Let $v_1v_2\dots v_k$ be a path with a path-arc representation such that $\text{cut}(v_1) = 0$. Then at least one of the graphs obtained from cutting before v_1 or after v_1 contains the path $v_1v_2\dots v_k$.



Reduction: circular-arc \rightarrow interval graphs

Lemma 2: Let $v_1v_2\dots v_k$ be a path such that $\sum_{i=1\dots k} \text{cut}(v_i)$ is the smallest possible across all paths on $\{v_1, v_2, \dots, v_k\}$ (and their representations). Then, $\text{right-cut}(v_1) = 0$.

Proof: By contradiction, $\text{right-cut}(v_1) > 0$.

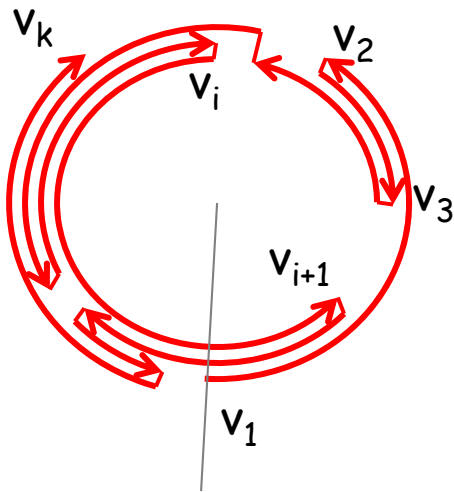


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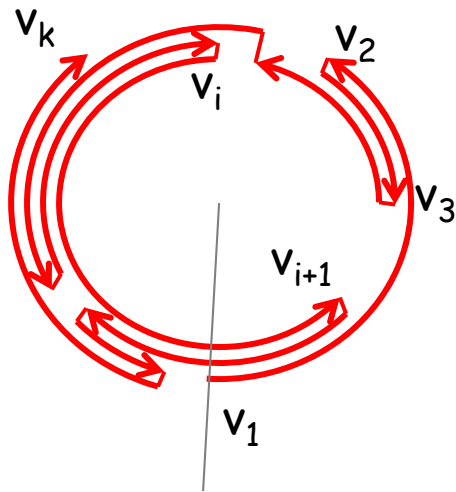
Let $v_i v_{i+1}$ be a right-going edge with red arc containing v_1 .



Reduction: circular-arc \rightarrow interval graphs

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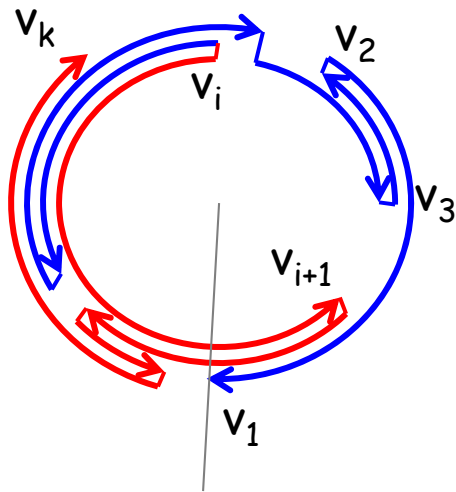
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Consider path $v_i v_{i-1} v_{i-2} \dots v_1 v_{i+1} v_{i+2} \dots v_k$.

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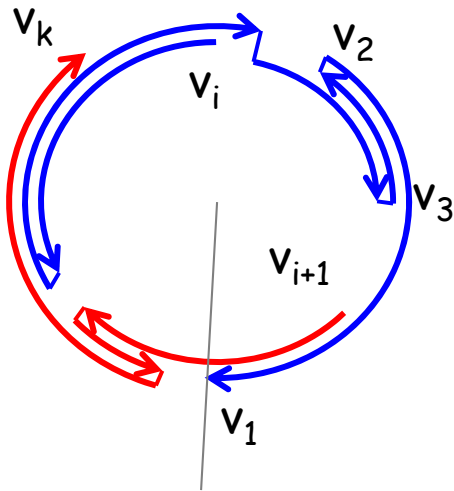
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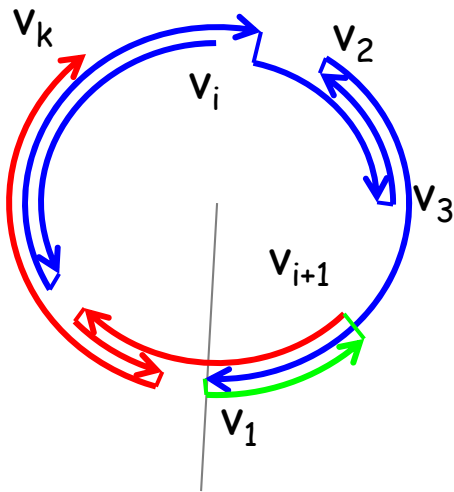
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Edge $v_i v_{i+1}$ disappeared.

Reduction: circular-arc \rightarrow interval graphs

Lemma 2: Let $v_1v_2\dots v_k$ be a path such that $\sum_{i=1\dots k} \text{cut}(v_i)$ is the smallest possible across all paths on $\{v_1, v_2, \dots, v_k\}$ (and their representations). Then, $\text{right-cut}(v_1) = 0$.

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Let $v_i v_{i+1}$ be a right-going edge with red arc containing v_1 .

Consider path $v_i v_{i-1} v_{i-2} \dots v_1 v_{i+1} v_{i+2} \dots v_k$.

Edge $v_i v_{i+1}$ disappeared.

What about edge $v_1 v_{i+1}$?

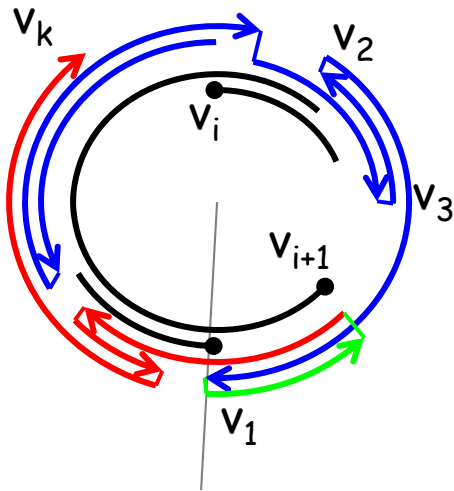
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Lemma 2: Let $v_1v_2\dots v_k$ be a path such that $\sum_{i=1\dots k} \text{cut}(v_i)$ is the smallest possible across all paths on $\{v_1, v_2, \dots, v_k\}$ (and their representations). Then, $\text{right-cut}(v_1) = 0$.

Proof: By contradiction, $\text{right-cut}(v_1) > 0$.

Claim: edge v_1v_{i+1} exists.

[Follows from existence of right-going edge $v_i v_{i+1}$.]

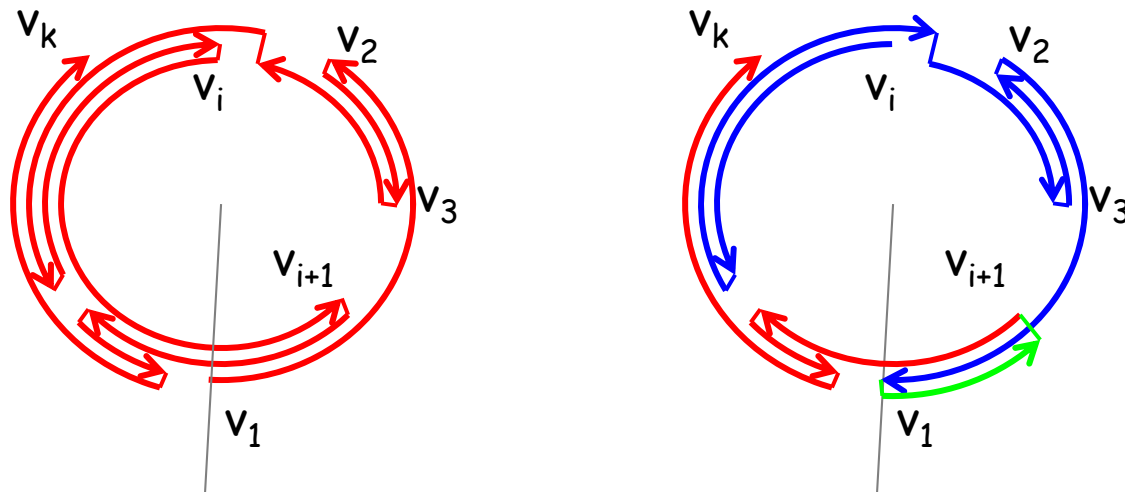


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Proof: By contradiction, $\text{right-cut}(v_1) > 0$.

The new path decreases $\sum_{i=1\dots k} \text{cut}(v_i)$, a contradiction. \square



Reduction: circular-arc \rightarrow interval graphs

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Corollary 2: Under the same conditions, $\text{left-cut}(v_k) = 0$.

Reduction: circular-arc \rightarrow interval graphs

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Corollary 2: Under the same conditions, $\text{left-cut}(v_k) = 0$.

Lemma 3: Under the same conditions, $\text{cut}(v_1) = 0$ or $\text{cut}(v_k) = 0$.

Reduction: circular-arc \rightarrow interval graphs

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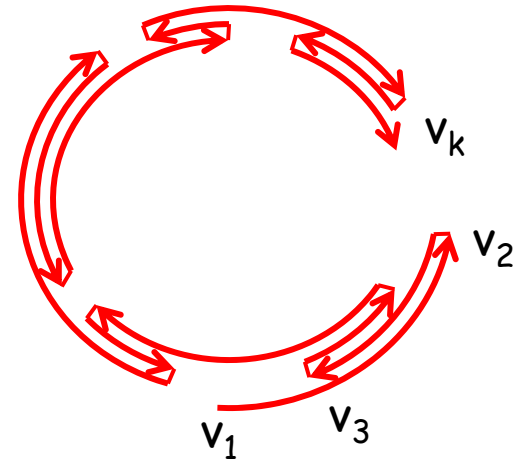
Theorem 1: For any path P there exists a path P' on the same vertex set and a vertex v such that the path P' is a path in the interval graph obtained by cutting the circle before v .

Reduction: circular-arc \rightarrow interval graphs

Lemma 3: Let $v_1v_2\dots v_k$ be a path such that $\sum_{i=1\dots k} \text{cut}(v_i)$ is the smallest possible across all paths on $\{v_1, v_2, \dots, v_k\}$ (and their representations). Then, $\text{cut}(v_1)=0$ or $\text{cut}(v_k)=0$.

Proof idea:

If v_1 's arc goes right and v_k 's arc comes from right, we get:



The full proof contains significant case analysis.

The idea of the simplified algorithm

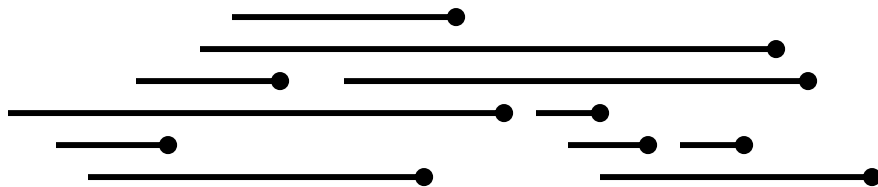
Some terminology:

- **normal paths** in interval graphs:

$v_1v_2\dots v_k$ is normal if

- v_1 is the left-most vertex

- for every i , v_i is the left-most neighbor of v_{i-1} out of all neighbors of v_{i-1} among $\{v_i, v_{i+1}, v_{i+2}, \dots, v_k\}$



The idea of the simplified algorithm

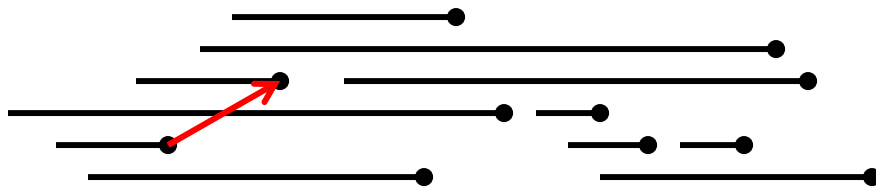
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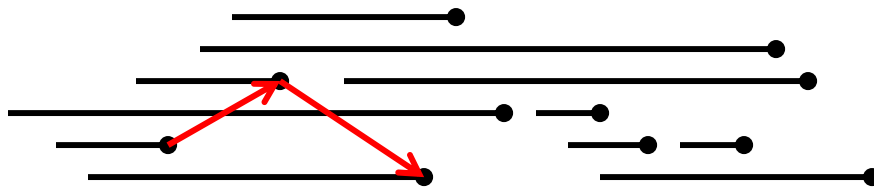
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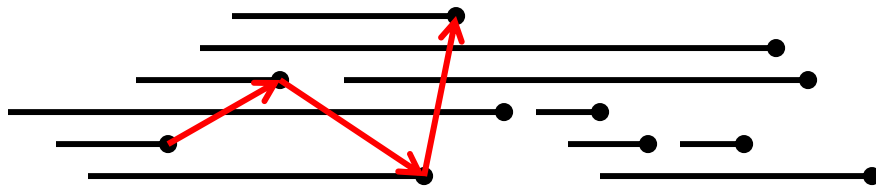
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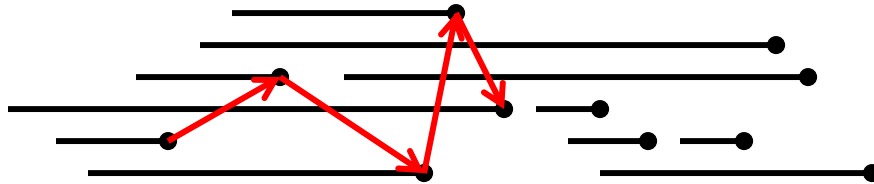
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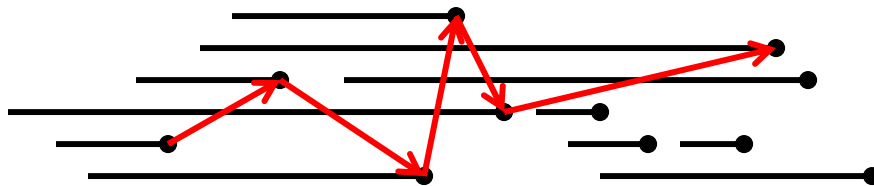
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$v_1v_2\dots v_k$ is normal if

- v_1 is the left-most vertex

- for every i , v_i is the left-most neighbor of v_{i-1} out of all neighbors of v_{i-1} among $\{v_i, v_{i+1}, v_{i+2}, \dots, v_k\}$



The idea of the simplified algorithm

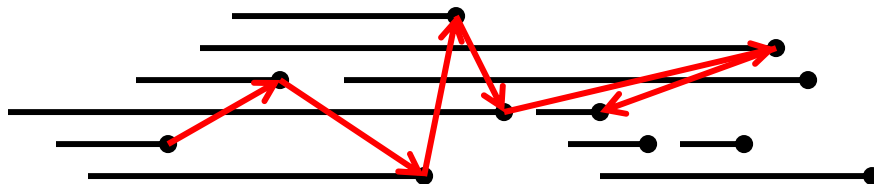
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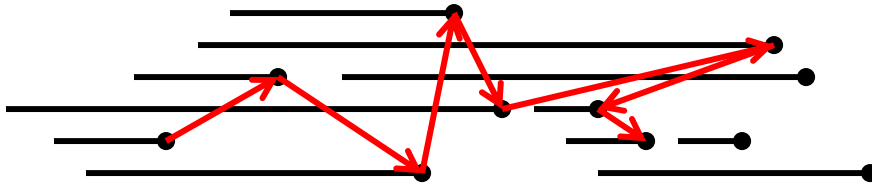
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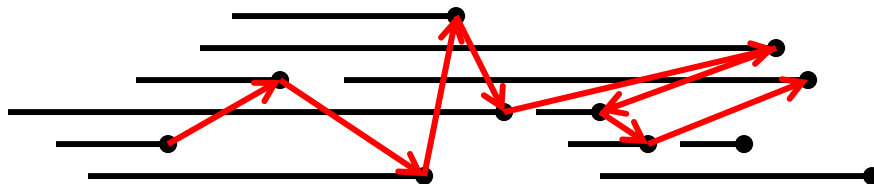
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The idea of the simplified algorithm

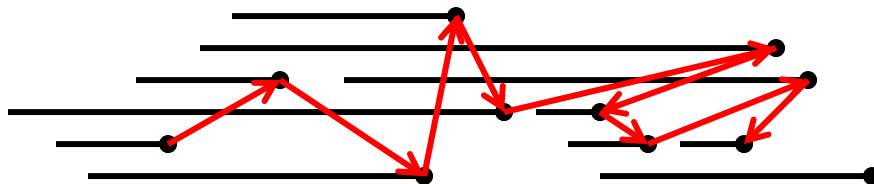
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The idea of the simplified algorithm

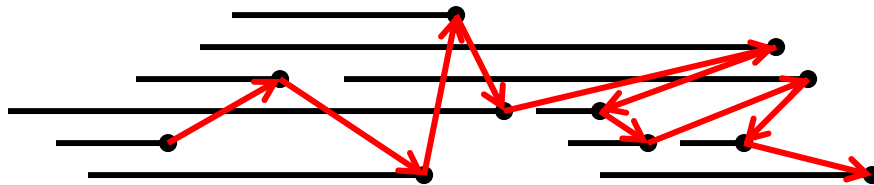
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The idea of the simplified algorithm

Some terminology:

- **normal paths** in interval graphs

[Ioannidou-Mertzios-Nikolopoulos '09]:

$v_1v_2\dots v_k$ is normal if

- v_1 is the left-most vertex

- for every i , v_i is the left-most neighbor of v_{i-1} out of all neighbors of v_{i-1} among $\{v_i, v_{i+1}, v_{i+2}, \dots, v_k\}$

Note:

similar notions introduced in [Damaschke '93, Keil '85]

The idea of the simplified algorithm

Some terminology:

- **normal paths** in circular-arc graphs:

$v_1v_2\dots v_k$ is normal if it is normal in the interval graph obtained by cutting the circle before a vertex u

Theorem 2: For every path P in a circular-arc graph there exists a normal path P' on the same vertex set as P .

The idea of the simplified algorithm

Algo for interval graphs [Ioannidou-Mertzios-Nikolopoulos '09]:

- runs in time $O(n^4)$
- for technical reasons uses special dummy nodes that do not (much) modify the length of the longest path

Algo for circular-arc graphs:

- runs in time $O(n^4)$ [avoids the extra cost of the reduction]
- does not need the dummy nodes; as a byproduct of this simplification, it can be used for counting the normal paths [exactly for interval graphs, n -approximation for circular-arc graphs]

The idea of the simplified algorithm

Algo for circular-arc graphs - idea:

- dynamic programming

- need the following:

- $G_i(j) :=$ induced subgraph of G_{u_i} with vertices $\{u_i, u_{i+1}, \dots, u_j\}$
where $i, j \in \{1, 2, \dots, n\}$

- $G(i, j) :=$ induced subgraph of G with vertices
 $\{u_i, u_{i+1}, \dots, u_j\} \setminus \{u_k \mid u_k \text{ contains the right endpoint of } u_{i-1}\}$
where $i, j \in \{1, 2, \dots, n\}$ and $j \neq i-1 \pmod n$

- $\ell_i(u_k, j) :=$ the length of a longest normal path of $G_i(j)$ with
 u_k as its last vertex

- $\ell(u_k, i, j) :=$ the length of a longest normal path of $G(i, j)$
with u_k as its last vertex

The idea of the simplified algorithm

Algo for circular-arc graphs - idea:

- why $O(n^4)$:

- two loops to go through all i, j pairs

- one loop for k

- one loop to consider an intermediate "joining" vertex that connects two shorter paths

- can keep track of the number of all normal paths corresponding to $l_i(u_k, j)$ and $l(u_k, i, j) \rightarrow$ a counting algorithm

Counting and sampling

Counting (and sampling) of normal paths:

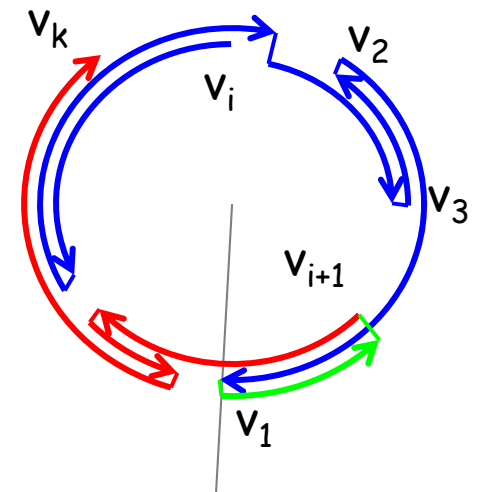
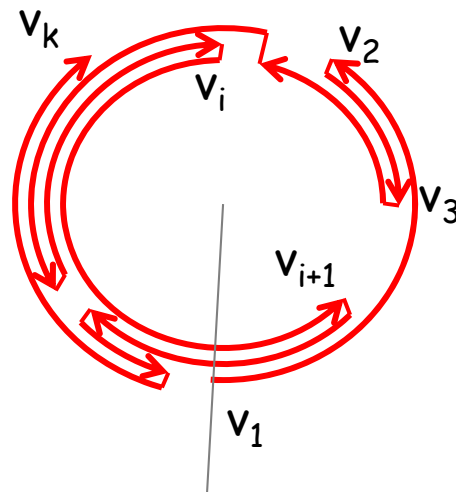
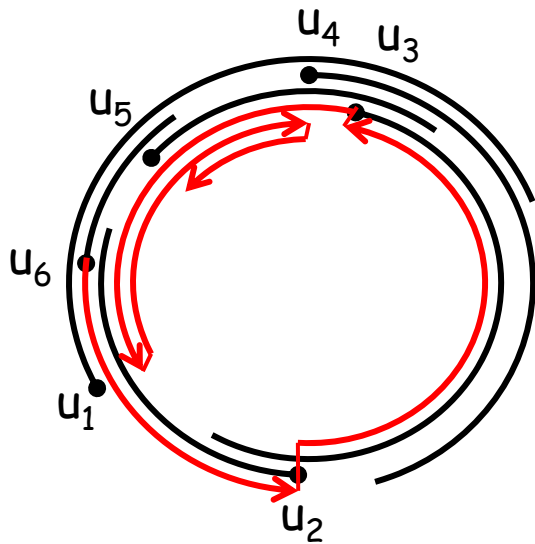
- in $O(n^4)$:
 - exact for interval graphs
 - n -approximation for circular-arc graphs
- for some graphs the number of normal paths can be exponentially large

Counting/sampling of paths considered in other works:

- #P-complete for general graphs [Dyer-Frieze-Jerrum '94]
- approx for special graph classes:
 - dense graphs [Dyer-Frieze-Jerrum '94], nearly regular [Frieze '00]
- self-avoiding walks in lattice graphs [Randall-Sinclair '00]

Open problems

Highlights from this talk:



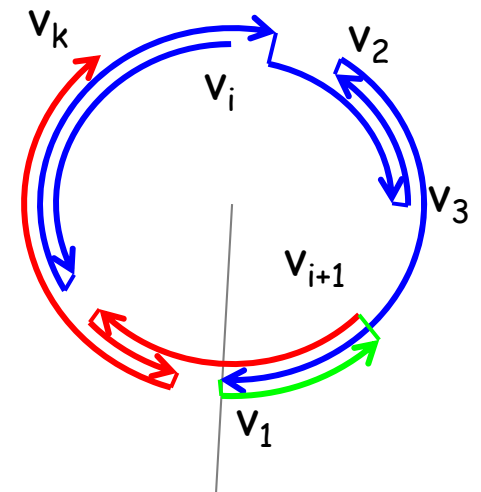
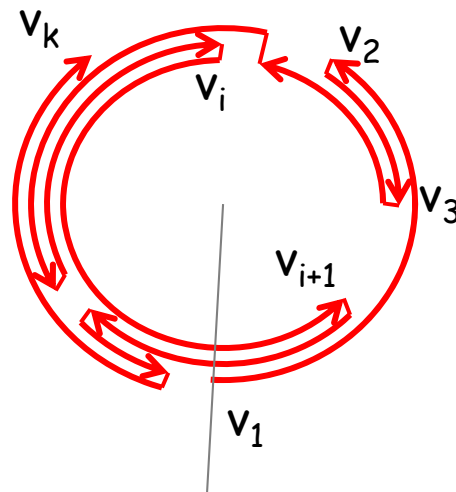
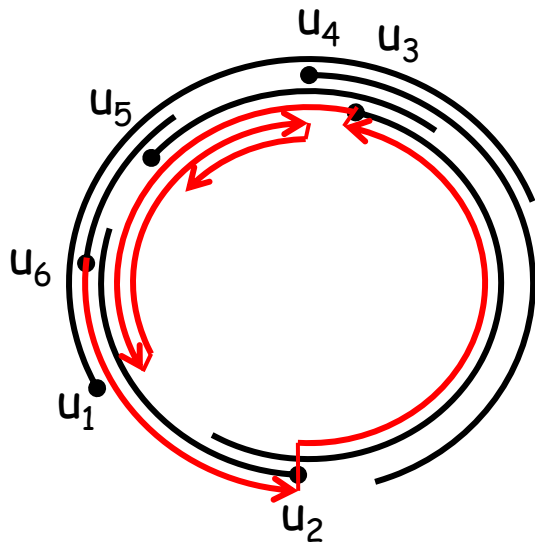
Open problems:

- count all longest paths in interval/circular-arc graphs
- improve the approximation ratio for counting normal paths in circular-arc graphs

Open problems

Highlights from this talk:

Thanks for your attention 😊



Open problems:

- count all longest paths in interval/circular-arc graphs
- improve the approximation ratio for counting normal paths in circular-arc graphs