



The Mechanics of Differential Evolution

Alexander G. Ororbia II

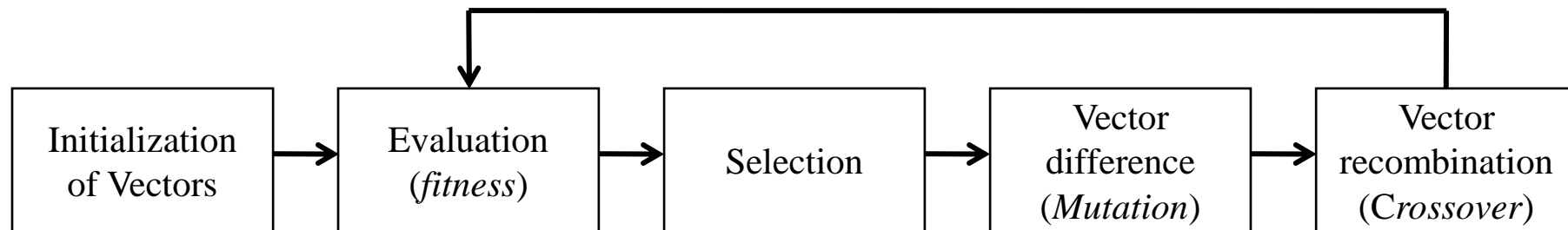
Biologically-Inspired Intelligent Systems

CSCI-633

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Metaheuristic: Differential Evolution (DE)

- Vector-based (population-based) algorithm; Storn & Price (1996/1997)
 - Viewed as self-organizing system
 - Individuals 'evolve' by recombination w/ other individuals & differentials between other individuals
- Devised for continuous search spaces, derivative-free
- No encoding/decoding required – real numbers are now solutions/chromosomes
- *DE/rand/1/bin*



DE General Mechanics

- Builds on the idea of genetic algorithms
- Three primary steps:
 - Mutation, crossover, selection
- Name convention: DE/x/y/z – x is mutation scheme, e.g., random (Rand) or best (Best), y is number of difference vectors, z is crossover scheme, e.g., binomial (Bin) or exponential (Exp) or either/agnostic (*)
 - We will start with: DE/Rand/1/*

Differential Evolution (Naming Convention)

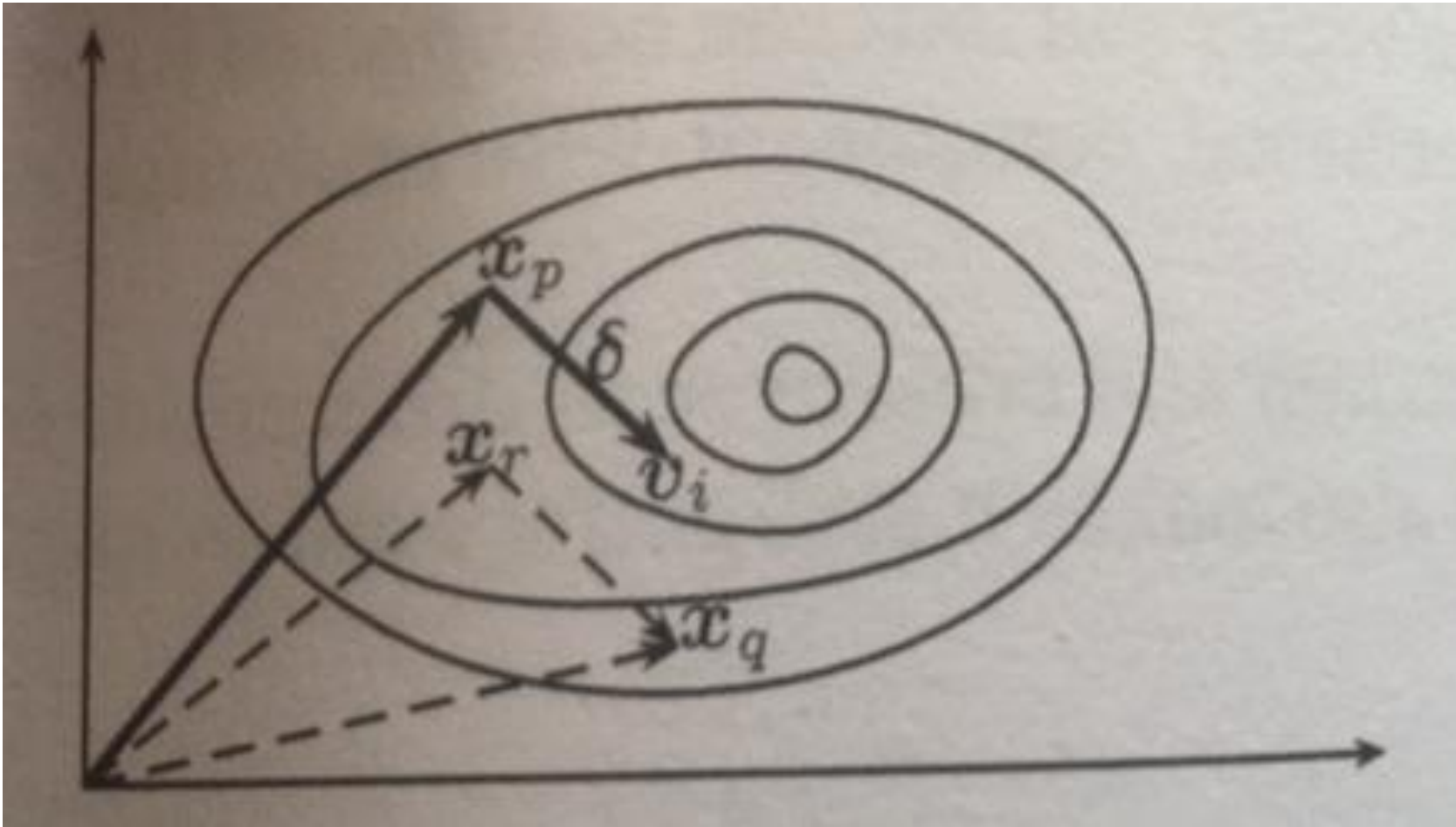
Many Variations:

- best/n/bin
- best/n/exp
- random/n/bin
- random/n/exp
- current/n/bin
- current/n/exp

Parent Selection / Number of Pairs / Recombination

- In general:
 - Perform binary or exponential recombination between current individual and another individual modified by a scaled difference between n pairs of other individuals



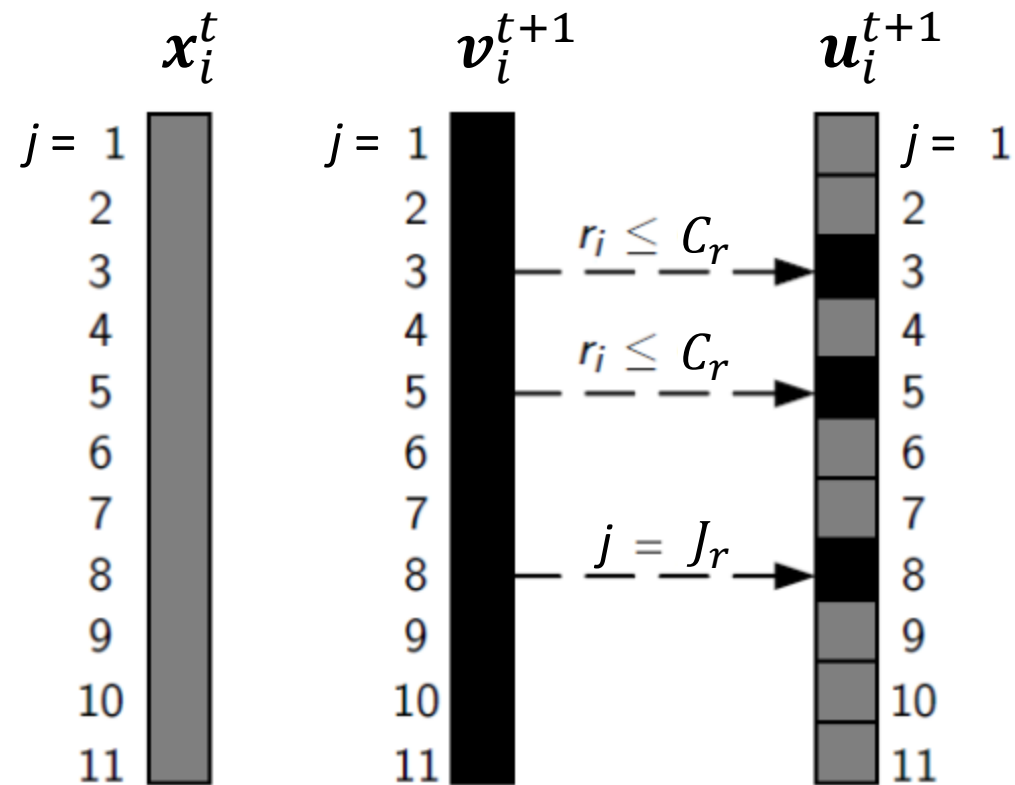


Schematic representation the application of a perturbation/mutation in DE, according to perturbation $\delta = \alpha(x_q^t - x_r^t)$ (movement along function space).



Binomial Crossover

- *Vector crossover visualization*





Pseudocode

Differential Evolution

Initialize the population \mathbf{x} with randomly generated solutions

Set the weight $F \in [0, 2]$ and crossover probability $C_r \in [0, 1]$

while (stopping criterion)

for $i = 1$ to n ,

 For each \mathbf{x}_i , randomly choose 3 distinct vectors \mathbf{x}_p , \mathbf{x}_r and \mathbf{x}_r

 Generate a new vector \mathbf{v} by DE scheme (6.2)

 Generate a random index $J_r \in \{1, 2, \dots, d\}$ by permutation

 Generate a randomly distributed number $r_i \in [0, 1]$

for $j = 1$ to d ,

 For each parameter $\mathbf{v}_{j,i}$ (j th component of \mathbf{v}_i), update

$$\mathbf{u}_{j,i}^{t+1} = \begin{cases} \mathbf{v}_{j,i}^{t+1} & \text{if } r_i \leq C_r \text{ or } j = J_r \\ \mathbf{x}_{j,i}^t & \text{if } r_i > C_r \text{ and } j \neq J_r, \end{cases}$$

end

 Select and update the solution by (6.5)

end

end

Post-process and output the best solution found

Figure 6.2 Pseudo code of differential evolution.

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Improves search efficiency by ensuring at least one dimension of perturbed solution is different from the original



Questions?

