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# Gradients and Algorithmic Perspectives

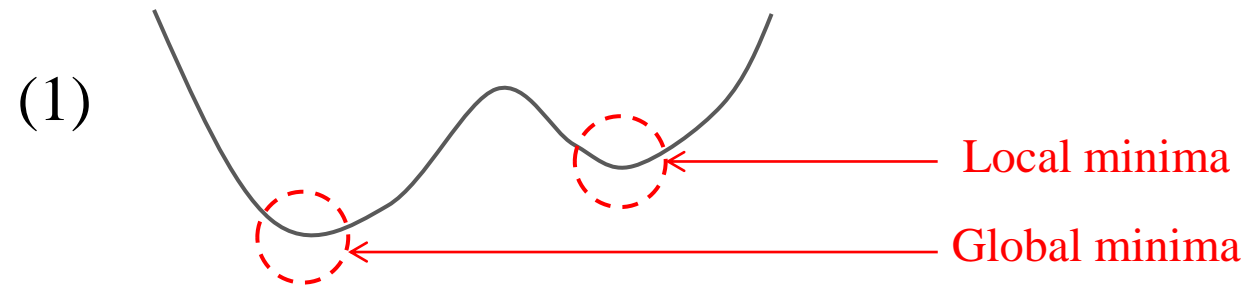
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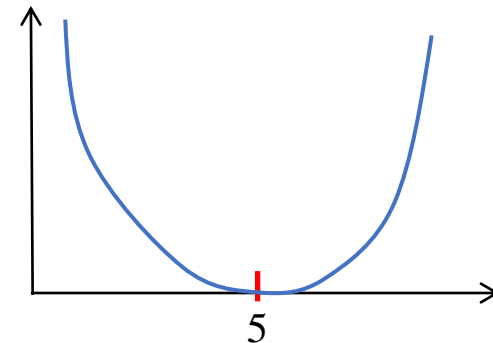
# Optimization through Derivatives

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- How would we solve the following problems?



(2)  $\min_w f(w) = (w-5)^2$   $\implies$  (a) Plot



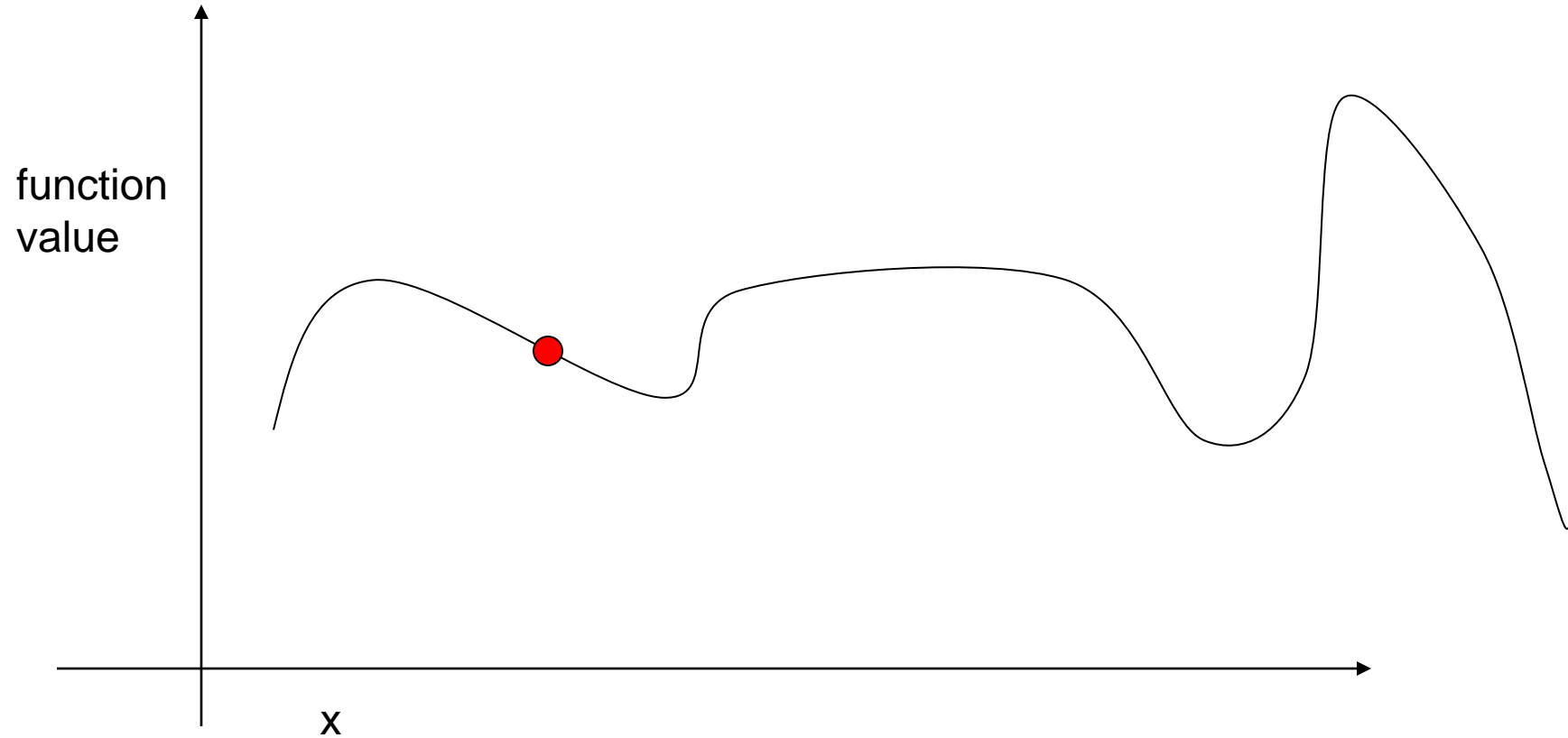
(b) Take *derivatives*, check = 0

# Following “Gradient Flows”



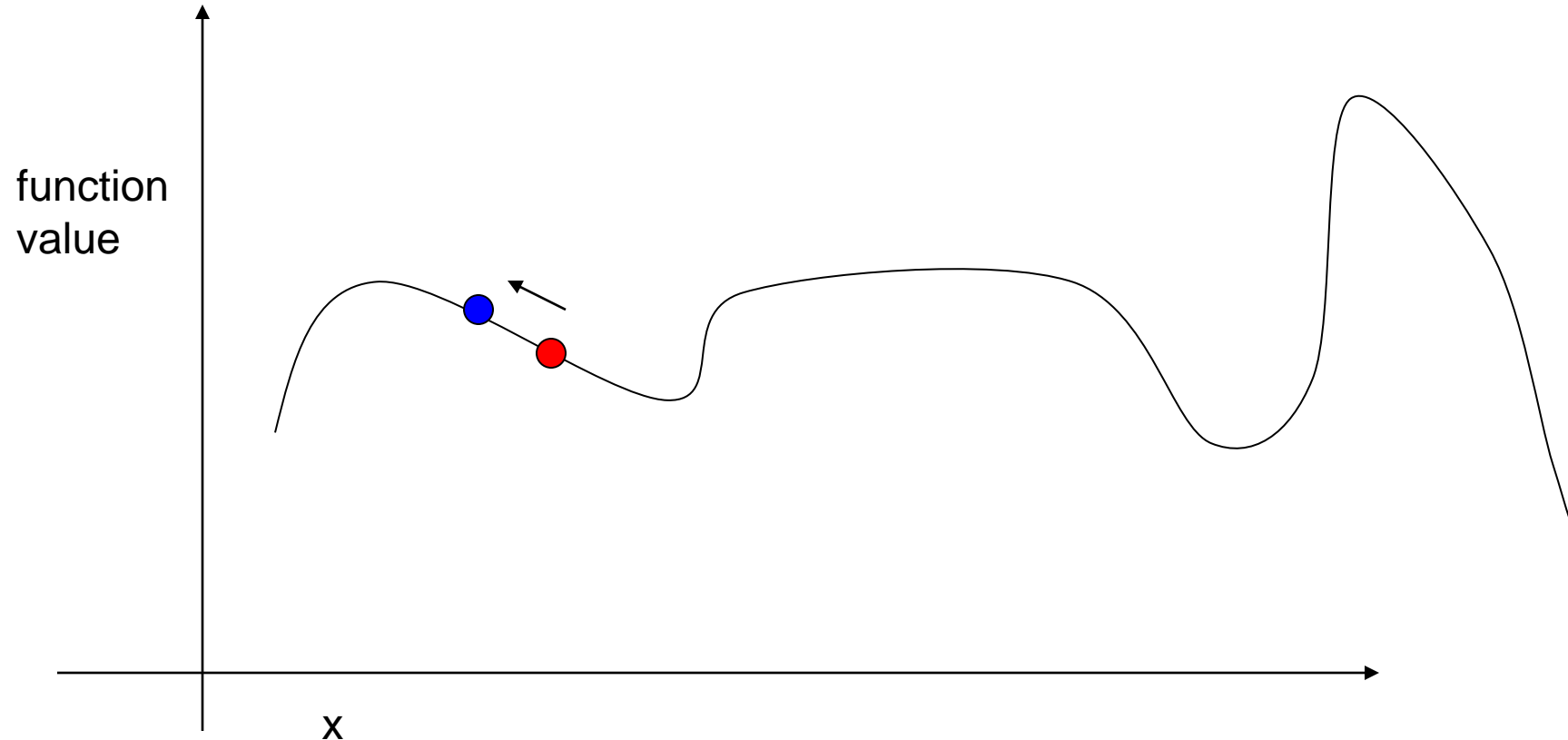
# Gradient Ascent

- Random Starting Point



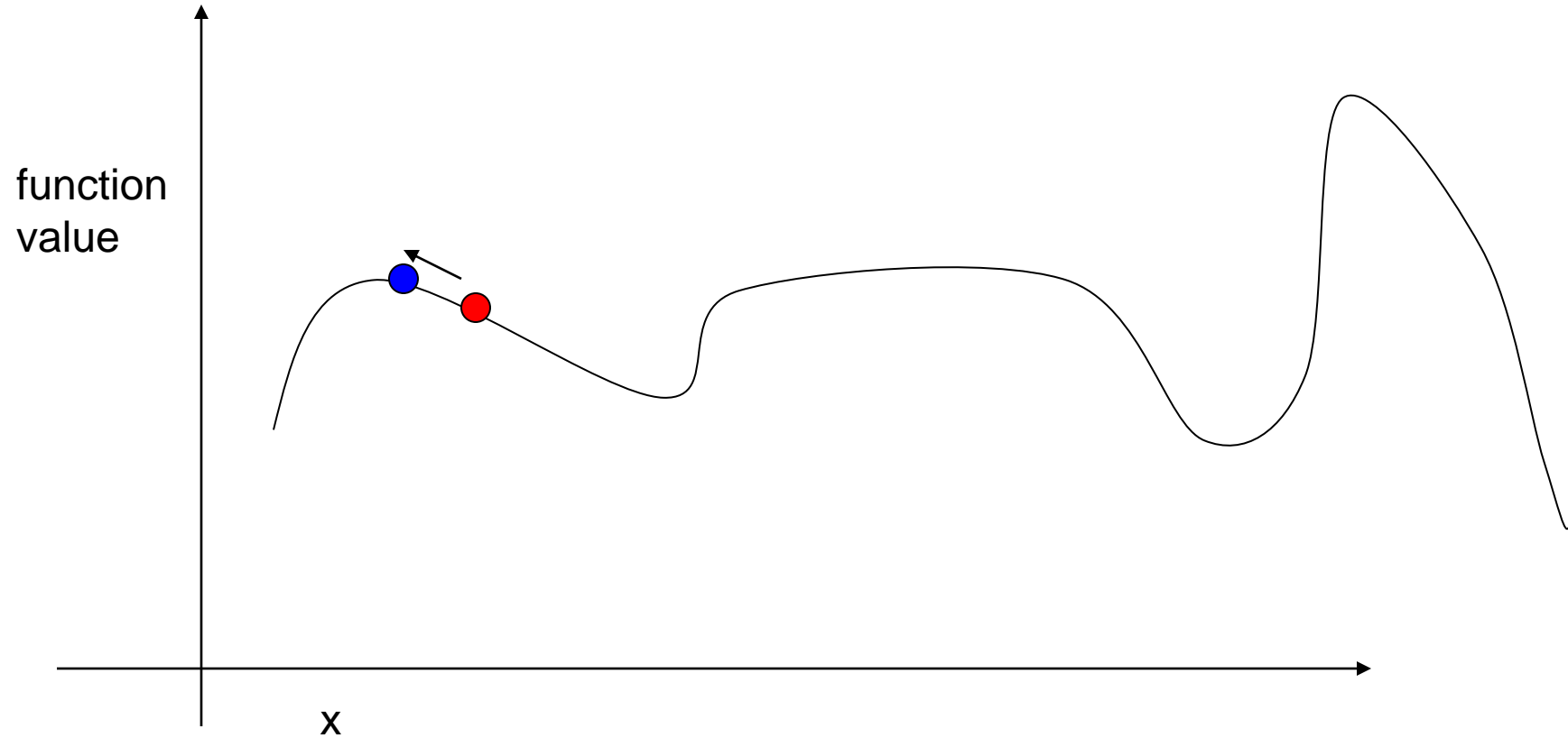
# Gradient Ascent

- Take step in direction of largest increase (obvious in 1D, must be computed in higher dimensions)



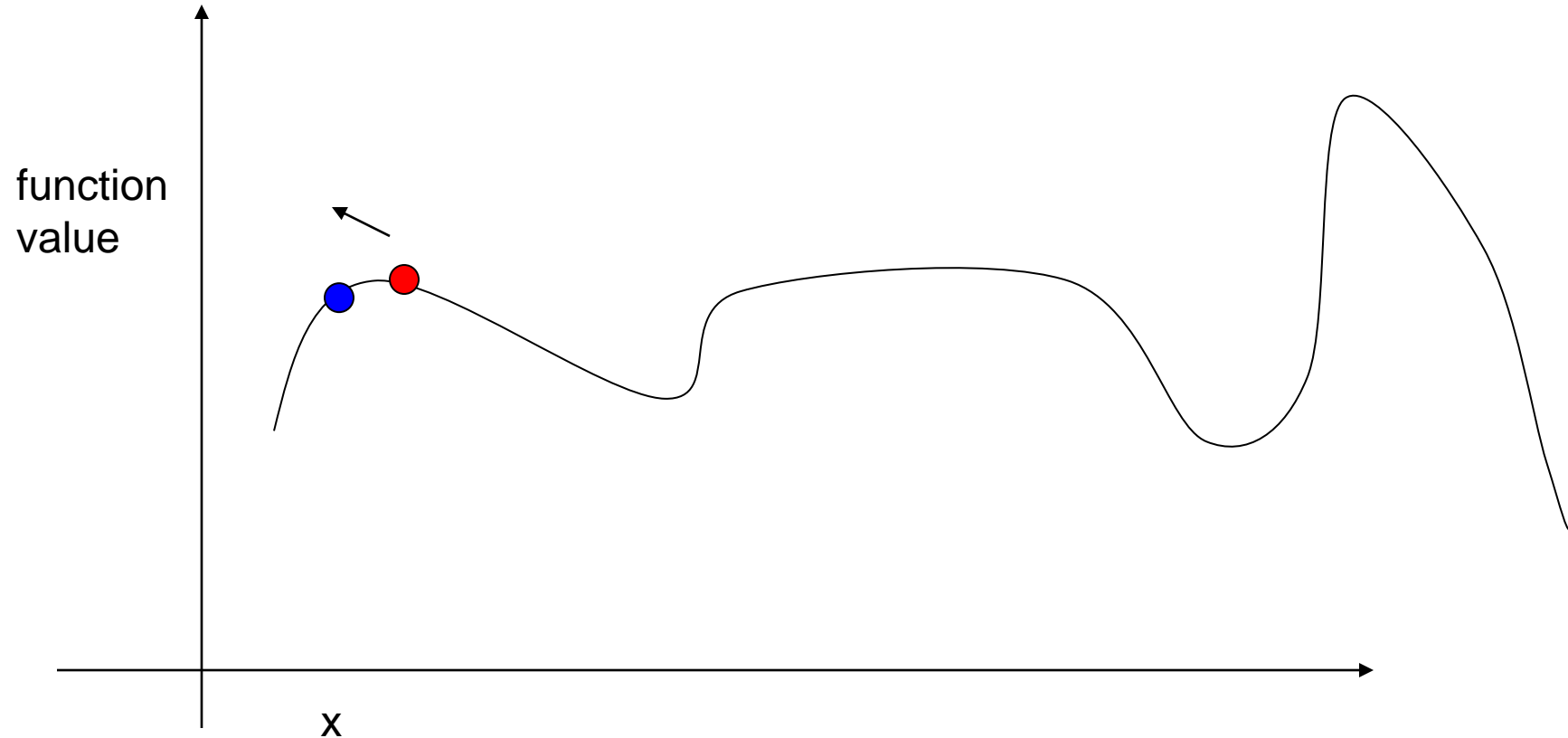
# Gradient Ascent

- Repeat



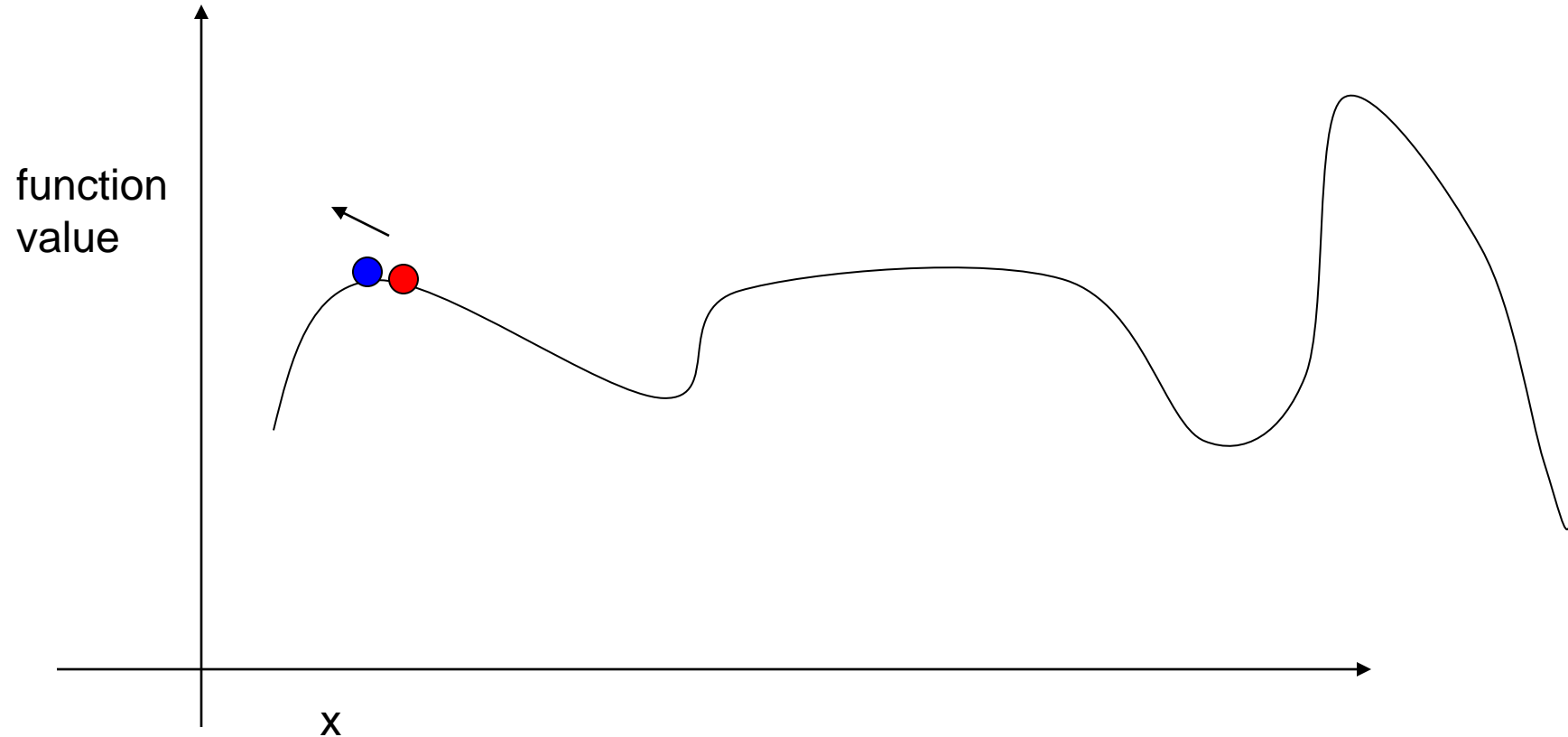
# Gradient Ascent

- Next step is actually lower, so stop



# Gradient Ascent

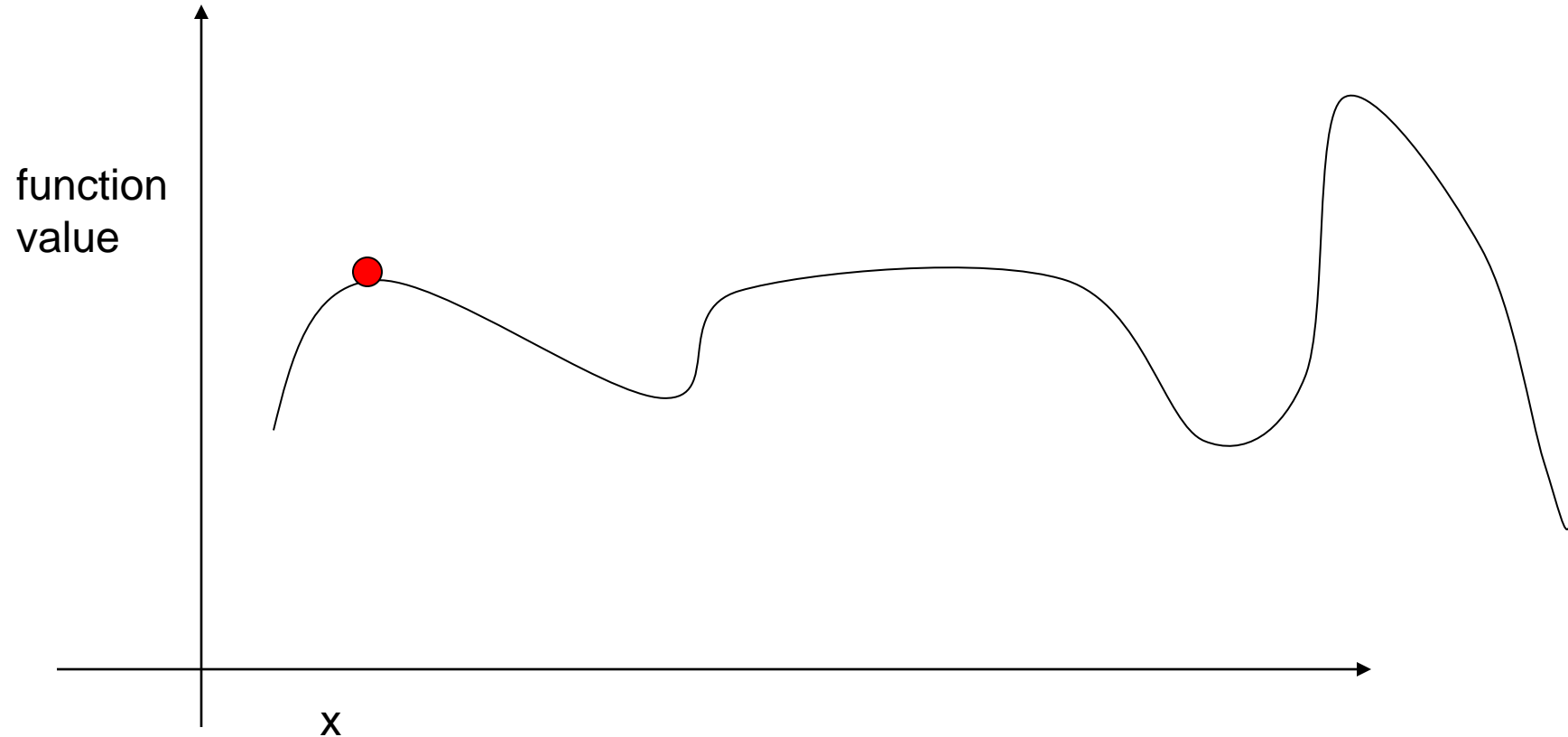
- Could reduce step size to “hone in”





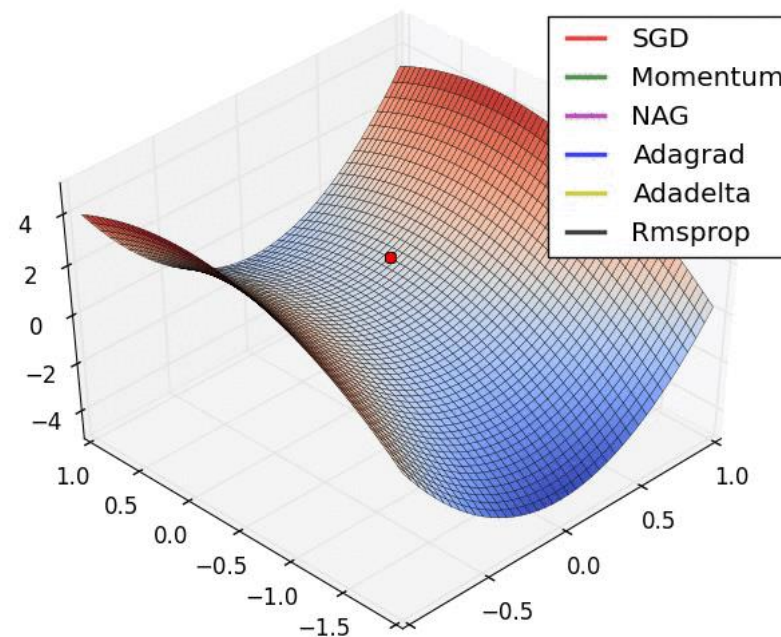
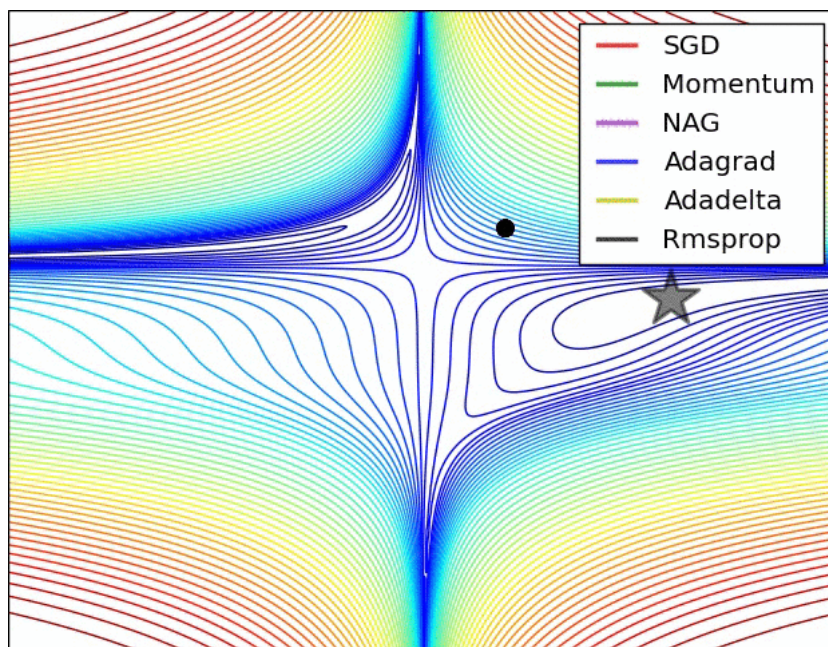
# Gradient Ascent

- Converge to (local) maximum



# Newton's Method

# Race of the Optimizers!



<http://cs231n.github.io/neural-networks-3/#hyper>

# Problem Specification/Formulation

- **General mathematical optimization (minimization) problem:**

minimize  $f_i(\mathbf{x}), i = 1, 2, \dots, M$

subject to  $h_j(\mathbf{x}) = 0, j = 1, 2, \dots, J$

$g_k(\mathbf{x}) \leq 0, k = 1, 2, \dots, K$

- $f_i: \mathbf{R}^d \rightarrow \mathbf{R}$ : objective/cost fcn (maps search/design space  $\rightarrow$  solution/response space)
- $\mathbf{x} = (x_1, \dots, x_d)^T$ : design variables - unknowns of the problem, could be mix of discrete & continuous (contus) values ( $\mathbf{x}$  is “design vector”)
- $h_j: \mathbf{R}^d \rightarrow \mathbf{R}$ : inequality constraints
- $g_k: \mathbf{R}^d \rightarrow \mathbf{R}$ : equality constraints
- This problem is a constrained optimization problem
  - Linear constraints + linear objectives  $\rightarrow$  linear programming problem

# Algorithmic View: An Iterative Process

- *[White board notes]*

Questions?

