

HOW?

- Place everything in an array based on search key value
  - Run the search key through an address calculator (the hash function)
  - Insert/retrieve from location specified by the hash function (address calculator)
- This scheme is termed hashing
  - The function is the hash function
  - The array is called a hash table

# Why not discard other data structures?

#### The mapping not always one-to-one

- A major drawback
- Results in collisions two items mapped to same location

• which adds complexity

- Ordered operations do not work well
- Making array large enough to avoid collisions seldom practical

## **Ordered Operations**

- We said earlier that hash tables don't work well for ordered operations
  - Now you should know enough to understand why
- Problems:
  - Display the users stored in a hash table alphabetically
  - Finding the lowest/highest values in a database
    To do these operations, we need to retrieve all the data in the hash table, sort or compare as we retrieve.

### **Typical Hash Function**

#### Must

- Be fast and easy to compute
- Place items evenly through the hash table
   More important, because the biggest performance loss is due to resolving collisions

#### **Different Hash Functions**

- Division and Remainder method
  - hash (key) = key % ARRAY\_SIZE
    Can distribute array items evenly by choosing a prime number for ARRAY\_SIZE
- Folding
  - Add the digits
  - hash(001364825) = 1+3+6+4+8+2+5 = 29
    Produces a normal distribution too bunched up

# Continued..

- Universal hashing
   -select hash function at random from designed class of functions
   Diff address for the same inputs
- Digit Rearrangement

   taking part of the original value or key , reversing of order, using that sequence of digits

# **Collision Resolving**

- Collision
  - 4567 % 101 = 22 = 7597 % 101 : collision
  - Two approaches to resolve
    - Alter the hash table to allow multiple entries per location
    - Allocate another location within the hash table

# Restructure Hash Table

- Multiple items stored in a single array location
  - Two schemes to do this
     Buckets
    - Separate chaining

### Buckets

- Each array location is itself an array called a bucket
  - Problem is choosing size of these arrays
     If too small, will fill up and must probe
    - If too large, wasted space

# Chaining

- Hash table is an array of linked lists
  - Each array element is a pointer to a linked list, the chain
    - Insertion: place at beginning of chain
    - Deletion/retrieval: search the appropriate chain

# Chaining

- Insertion is O(1)
- Deletion/retrieval depend on chain length

#### Searching

- $(1 + \alpha)$  for successful search
- $(1 + \alpha)$  for unsuccessful search
- Best case: O(1), worst case: O(N)

### **Open Addressing**

- Open Addressing
- Probe for another empty, open location
  - Linear Probing
  - Quadratic probing
  - Double Hashing

# Linear probing

 Probe sequentially until an empty spot is found

Given key K

First slot probed T[h'(k)], if collision continue T[h'(k)+1]..... Up to T[m-1]

- Wrap around if you get to the end
  - Additions straightforward
  - Deletions pose a problem

# **Problems of Linear Probing**

- Items tend to cluster together in consecutively occupied locations
  - Termed primary clustering
  - A cluster tends to increase in size
  - Clusters can merge into larger clusters
  - Increase the average search time
  - Primary clustering makes linear probing inefficient

#### Quadratic probing

- Uses a hash function
  - $h(k,i) = (h'(k)+C_1 i + C_2 i^2) \mod m$
- $C_1 C_2$  auxillary constants
- i = 0 ,....,m-1
  - Positions are offset in a quadratic manner
- Virtually eliminates primary clusters
- Suffers from secondary clustering since same probe sequence used to resolve collision at original location

# **Double Hashing**

- Best methods of open addressing
- Uses a hash function
  - $h(k,i) = (h_1(k) + ih_2(k)) \mod m$
  - $h_{1,}h_{2}$  auxillary hash functions
- Drastically reduces clustering
- Previous methods are key independent
- Double hashing uses key-dependent probe sequences

## Continued

- Choose first function hash() as usual
- Follow these guidelines for hash2()
  - hash2(key) != 0
  - hash2() != hash()

# Hashing Efficiency

- $\bullet$  Involves the load factor  $\alpha$ 
  - $\alpha$  = average # of elements
  - $\bullet \, \alpha$  is a measure of how full the table is
  - As the hash table fills
  - $\alpha$  increases
  - Chance of collision increases
  - Search time increases
     Hashing efficiency decreases

# **Linear Probing**

- As collisions increase
  - Probe sequence increases
  - Search time increases
  - $\bullet\,\alpha$  should not exceed 2/3 for linear probing
- Best case : O(1)
- Worst Case :  $O(1 + \alpha)$

# Quadratic probing ,Double Hashing

- On average, both require fewer comparisons than linear probing
  - For  $\alpha$  = 2/3, avg unsuccessful search might require at most 3 compares, successful 2
- All three open addressing schemes suffer when unable to predict number of insertions and deletions as table may be too small

# **Good Hash Function**

- Easy and fast to compute
- Scatter data evenly through table
  - Check for various types of data
    - Random dataNonrandom data
  - Two general principles for even distribution
    - Use the whole key
    - If modulo math, base should be prime



# References

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